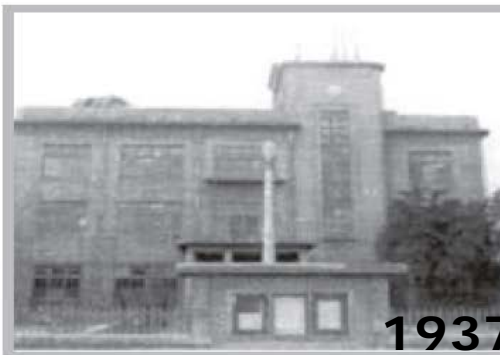




中央氣象局數值模式產品介紹及 跨域應用經驗分享

洪景山

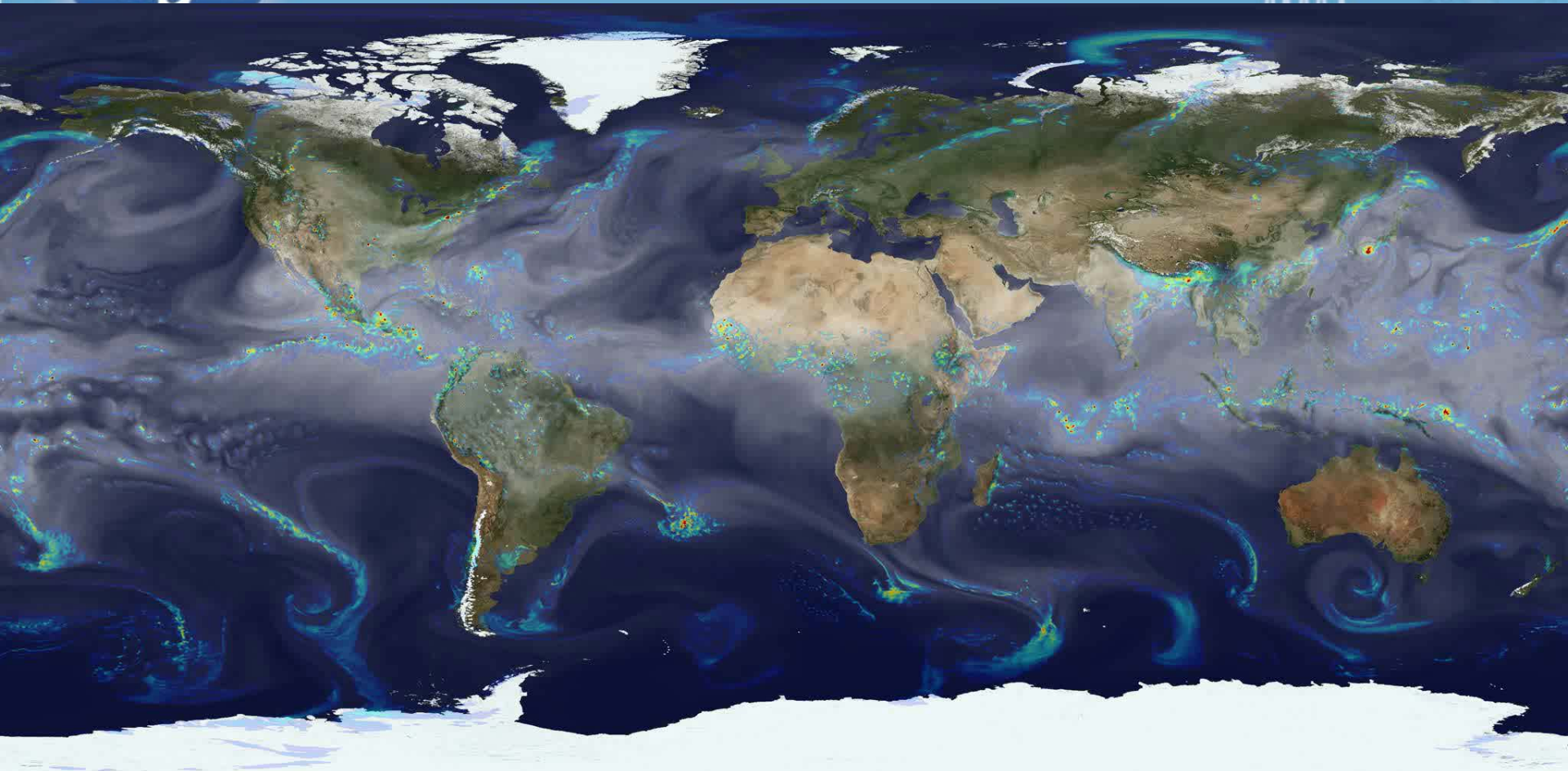
交通部中央氣象局





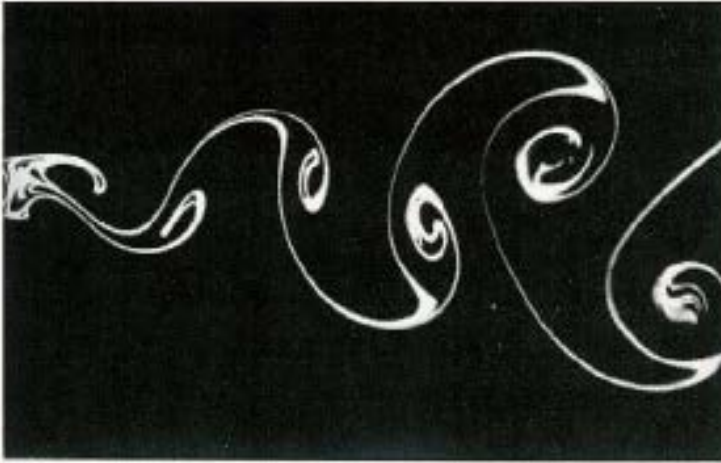
「數值天氣預報」是天氣預報的基礎
過去是，現在是，未來也將是

什麼是「數值天氣預報」

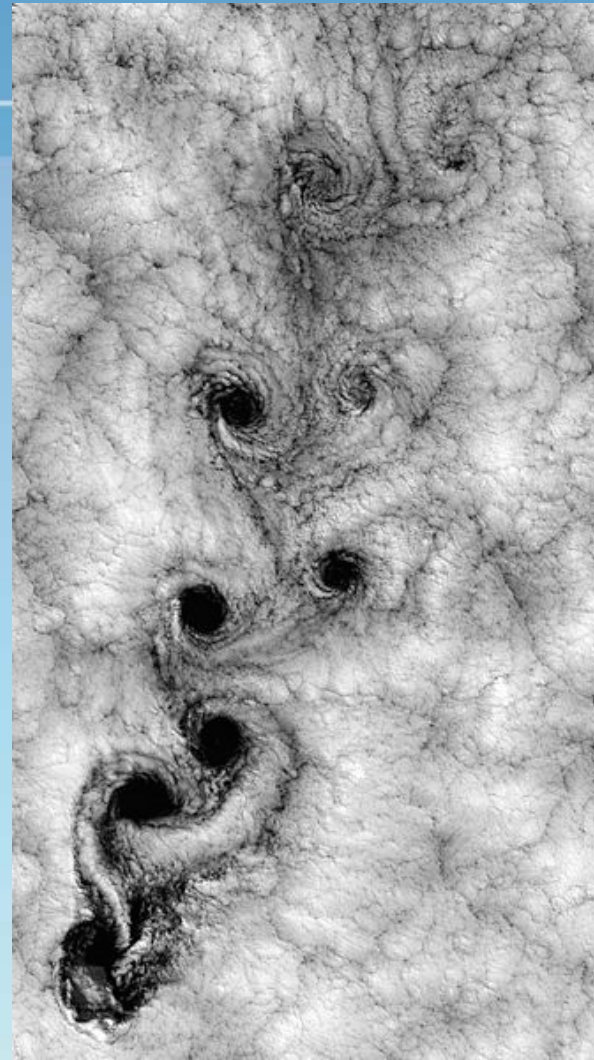


Atmospheric motion, looks like the flow of the fluid
Weather forecast: To predict the motion of the flow

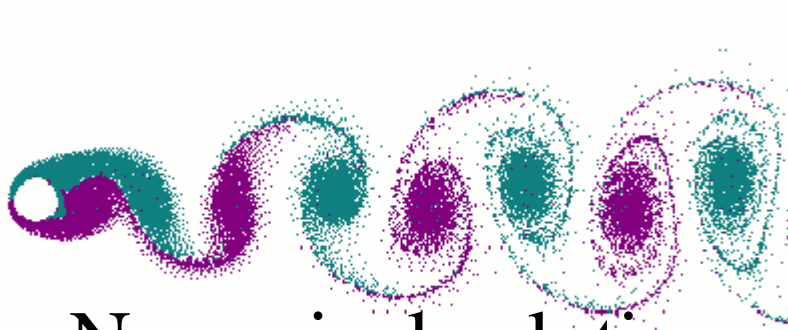
Hydraulic experiment



Atmospheric observation



$\frac{Du}{\partial t} + H \frac{\partial u}{\partial x} + H \frac{\partial v}{\partial y} = 0$



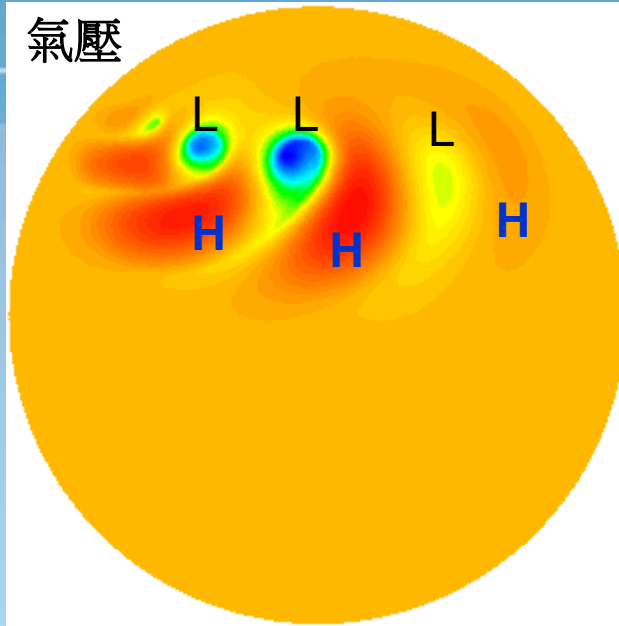
Numerical solution

$$\frac{\partial u}{\partial t} + H \frac{\partial u}{\partial x} + H \frac{\partial v}{\partial y} = 0$$

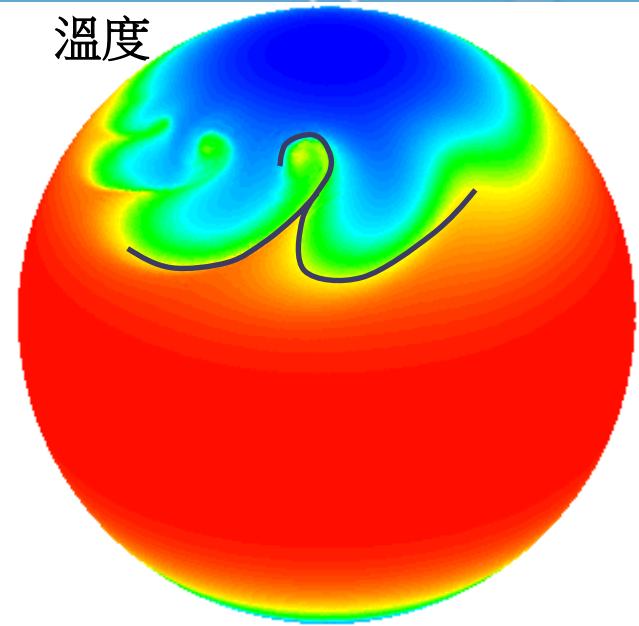
Shallow water equation



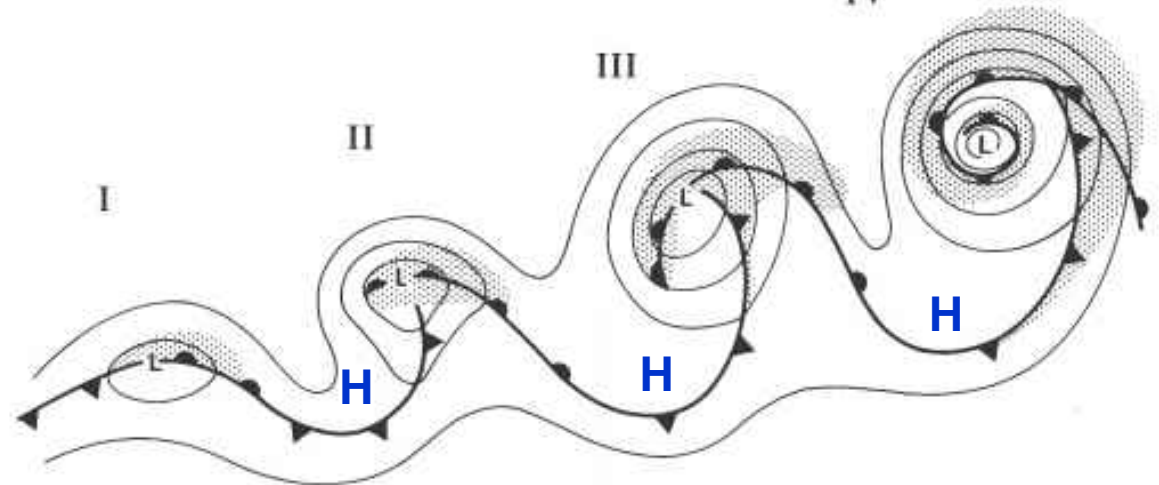
氣壓



溫度



IV



$$\frac{Du}{Dt} - fv = -g \frac{\partial \eta}{\partial x}$$

$$\frac{Dv}{Dt} + fu = -g \frac{\partial \eta}{\partial y}$$

$$\frac{\partial \eta}{\partial t} + H \frac{\partial u}{\partial x} + H \frac{\partial v}{\partial y} = 0$$



Equations to govern the atmospheric motion

$$\partial_t U + (\nabla \cdot \mathbf{V}u)_\eta + \mu_d \alpha \partial_x p + (\alpha/\alpha_d) \partial_\eta p \partial_x \phi = F_U$$

$$\partial_t V + (\nabla \cdot \mathbf{V}v)_\eta + \mu_d \alpha \partial_y p + (\alpha/\alpha_d) \partial_\eta p \partial_y \phi = F_V$$

$$\partial_t W + (\nabla \cdot \mathbf{V}w)_\eta - g[(\alpha/\alpha_d) \partial_\eta p - \mu_d] = F_W$$

$$\partial_t \Theta + (\nabla \cdot \mathbf{V}\theta)_\eta = F_\Theta$$

$$\partial_t \mu_d + (\nabla \cdot \mathbf{V})_\eta = 0$$

$$\partial_t \phi + \mu_d^{-1} [(\mathbf{V} \cdot \nabla \phi)_\eta - gW] = 0$$

$$\partial_t Q_m + (\mathbf{V} \cdot \nabla q_m)_\eta = F_{Q_m}$$

$$\begin{aligned} \partial_t U + m[\partial_x(Uu) + \partial_y(Vu)] + \partial_\eta(\Omega u) + (\mu_d \alpha \partial_x p' + \mu_d \alpha' \partial_x \bar{p}) \\ + (\alpha/\alpha_d)(\mu_d \partial_x \phi' + \partial_\eta p' \partial_x \phi - \mu_d' \partial_x \phi) = F_U \end{aligned} \quad (2.35)$$

$$\begin{aligned} \partial_t V + m[\partial_x(Uv) + \partial_y(Vv)] + \partial_\eta(\Omega v) + (\mu_d \alpha \partial_y p' + \mu_d \alpha' \partial_y \bar{p}) \\ + (\alpha/\alpha_d)(\mu_d \partial_y \phi' + \partial_\eta p' \partial_y \phi - \mu_d' \partial_y \phi) = F_V \end{aligned} \quad (2.36)$$

$$\begin{aligned} \partial_t W + m[\partial_x(Uw) + \partial_y(Vw)] + \partial_\eta(\Omega w) \\ - m^{-1} g(\alpha/\alpha_d)[\partial_\eta p' - \bar{\mu}_d(q_v + q_c + q_r)] + m^{-1} \mu_d' g = F_W, \end{aligned} \quad (2.37)$$

and the mass conservation equation (2.27) and geopotential equation (2.28) become

$$\partial_t \mu_d' + m^2[\partial_x U + \partial_y V] + m \partial_\eta \Omega = 0 \quad (2.38)$$

$$\partial_t \phi' + \mu_d^{-1}[m^2(U\phi_x + V\phi_y) + m\Omega\phi_\eta - gW] = 0. \quad (2.39)$$

Remaining unchanged are the conservation equations for the potential temperature and scalars

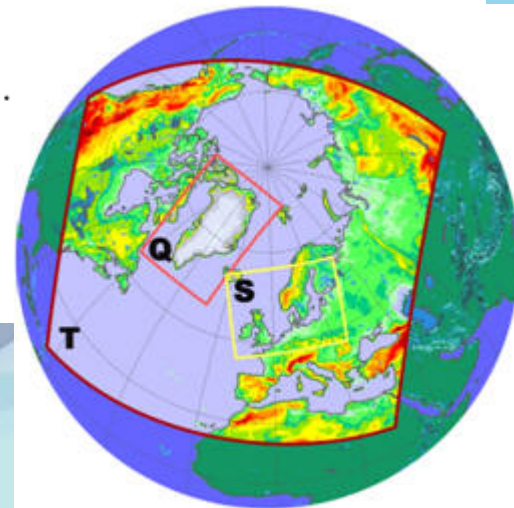
$$\partial_t \Theta + m^2[\partial_x(U\theta) + \partial_y(V\theta)] + m \partial_\eta(\Omega\theta) = F_\Theta$$

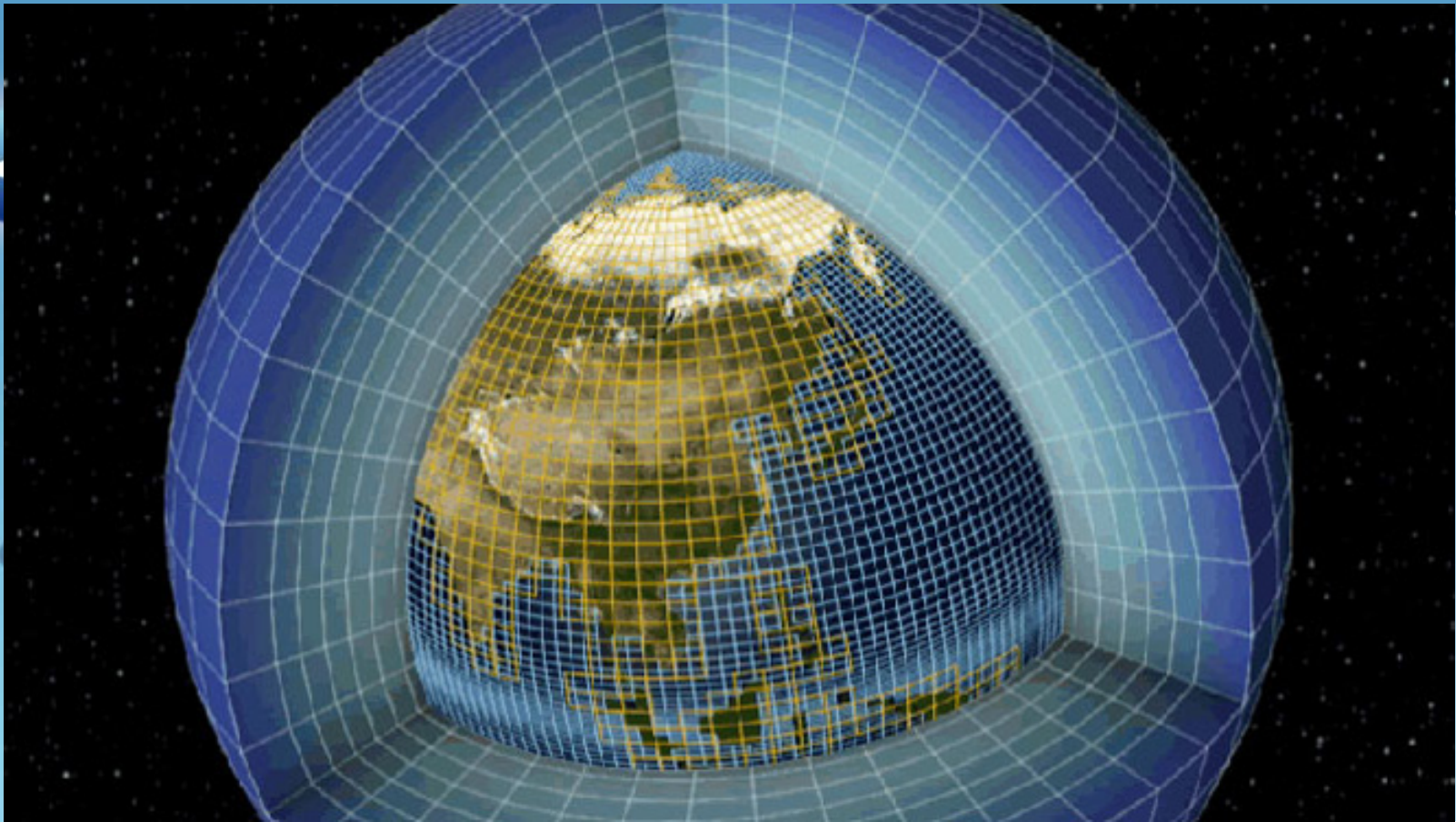
$$\partial_t Q_m + m^2[\partial_x(Uq_m) + \partial_y(Vq_m)] + m \partial_\eta(\Omega q_m) = F_{Q_m}.$$

In the perturbation system the hydrostatic relation (2.30) becomes

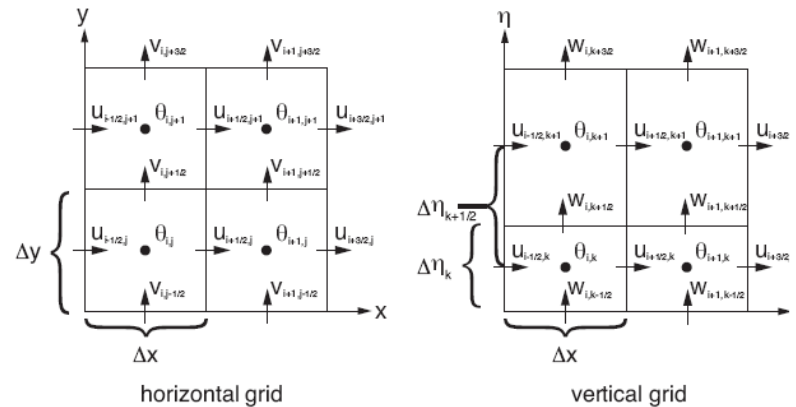
$$\partial_\eta \phi' = -\bar{\mu}_d \alpha_d' - \alpha_d \mu_d'.$$

Project to the earth coordinate





- Discretize the governing equation to the grid system



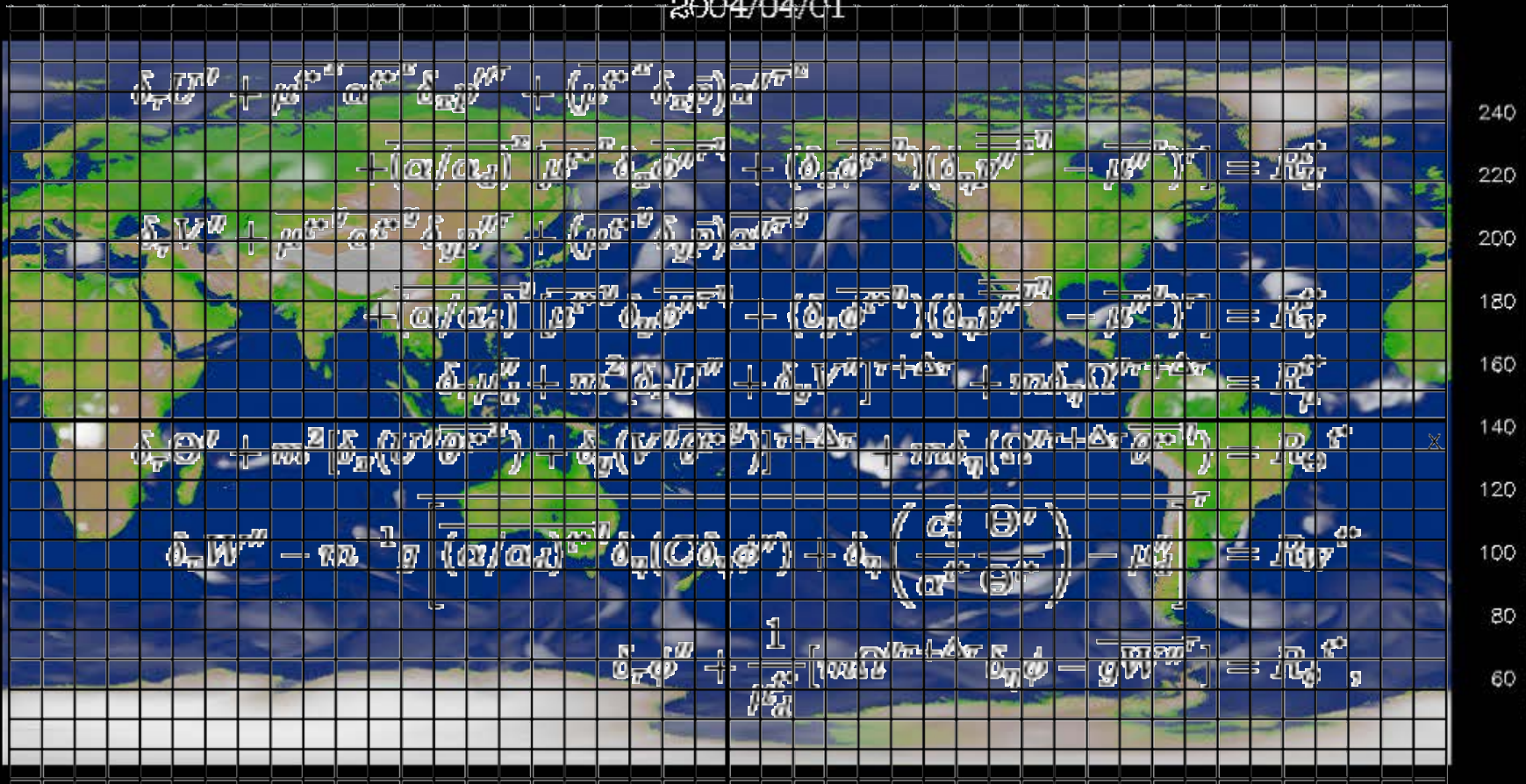
$$\begin{aligned}
& \delta_\tau U'' + \overline{\mu^{t^*x} \alpha^{t^*x}} \delta_x p''^\tau + (\overline{\mu^{t^*x} \delta_x \bar{p}}) \overline{\alpha''^{\tau x}} \\
& \quad + \overline{(\alpha/\alpha_d)^x} [\overline{\mu^{t^*x} \delta_x \overline{\phi''^{\tau\eta}}} + (\delta_x \overline{\phi^{t^*\eta}}) (\delta_\eta \overline{p''^{\tau\eta}} - \overline{\mu''^{\tau x}})^\tau] = R_U^{t^*} \\
& \delta_\tau V'' + \overline{\mu^{t^*y} \alpha^{t^*y}} \delta_y p''^\tau + (\overline{\mu^{t^*y} \delta_y \bar{p}}) \overline{\alpha''^{\tau y}} \\
& \quad + \overline{(\alpha/\alpha_d)^y} [\overline{\mu^{t^*y} \delta_y \overline{\phi''^{\tau\eta}}} + (\delta_y \overline{\phi^{t^*\eta}}) (\delta_\eta \overline{p''^{\tau\eta}} - \overline{\mu''^{\tau y}})^\tau] = R_V^{t^*} \\
& \delta_\tau \mu_d'' + m^2 [\delta_x U'' + \delta_y V'']^{\tau+\Delta\tau} + m \delta_\eta \Omega''^{\tau+\Delta\tau} = R_\mu^{t^*} \\
& \delta_\tau \Theta'' + m^2 [\delta_x (U'' \overline{\theta^{t^*x}}) + \delta_y (V'' \overline{\theta^{t^*y}})]^{\tau+\Delta\tau} + m \delta_\eta (\Omega''^{\tau+\Delta\tau} \overline{\theta^{t^*\eta}}) = R_\Theta^{t^*} \\
& \delta_\tau W'' - m^{-1} g \left[\overline{(\alpha/\alpha_d)^{t^*\eta} \delta_\eta (C \delta_\eta \phi'')} + \delta_\eta \left(\frac{c_s^2}{\alpha^{t^*}} \frac{\Theta''}{\Theta^{t^*}} \right) - \mu_d'' \right]^\tau = R_W^{t^*} \\
& \delta_\tau \phi'' + \frac{1}{\mu_d^{t^*}} [m \Omega''^{\tau+\Delta\tau} \delta_\eta \phi - \overline{g W''^\tau}] = R_\phi^{t^*},
\end{aligned}$$

$$\begin{aligned}
R_U^{t^*} &= - (\overline{\mu_d^x \alpha^x} \delta_x p' - \overline{\mu_d^x \alpha^x} \delta_x \bar{p}) - \overline{(\alpha/\alpha_d)^x} (\overline{\mu_d^x \delta_x \overline{\phi''^\eta}} - \delta_\eta \overline{p''^{\tau\eta}} \delta_x \overline{\phi''^\eta} + \overline{\mu_d^x} \delta_x \overline{\phi''^\eta}) \\
& \quad + F_{U_{cor}} + \text{advection} + \text{mixing} + \text{physics} \\
R_V^{t^*} &= - (\overline{\mu_d^y \alpha^y} \delta_y p' - \overline{\mu_d^y \alpha^y} \delta_y \bar{p}) - \overline{(\alpha/\alpha_d)^y} (\overline{\mu_d^y \delta_y \overline{\phi''^\eta}} - \delta_\eta \overline{p''^{\tau\eta}} \delta_y \overline{\phi''^\eta} + \overline{\mu_d^y} \delta_y \overline{\phi''^\eta}) \\
& \quad + F_{V_{cor}} + \text{advection} + \text{mixing} + \text{physics} \\
R_W^{t^*} &= m^{-1} g \overline{(\alpha/\alpha_d)^\eta} [\delta_\eta p' + \overline{\mu_d q_m^\eta}] - m^{-1} \mu_d' g \\
& \quad + F_{W_{cor}} + \text{advection} + \text{mixing} + \text{buoyancy} + \text{physics}.
\end{aligned}$$

Numerical weather prediction (NWP)

→ The numerical solution of the fluid dynamic equations

2004/04/01

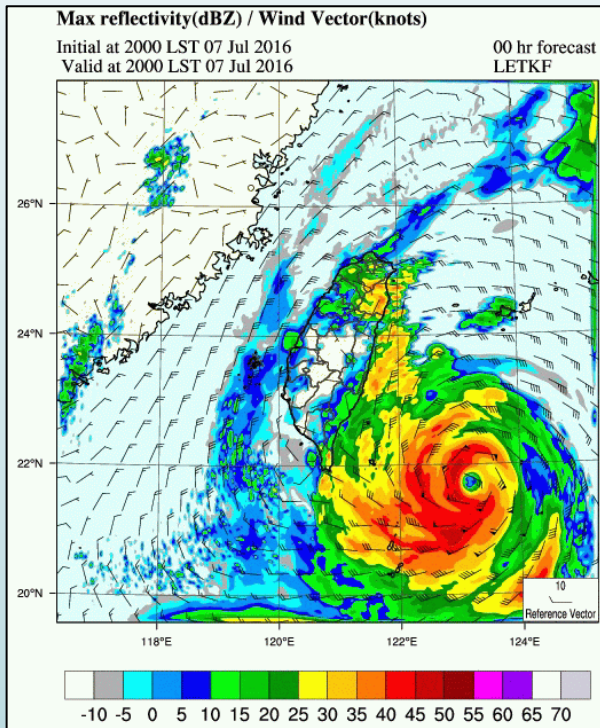


Is it a real atmosphere ?

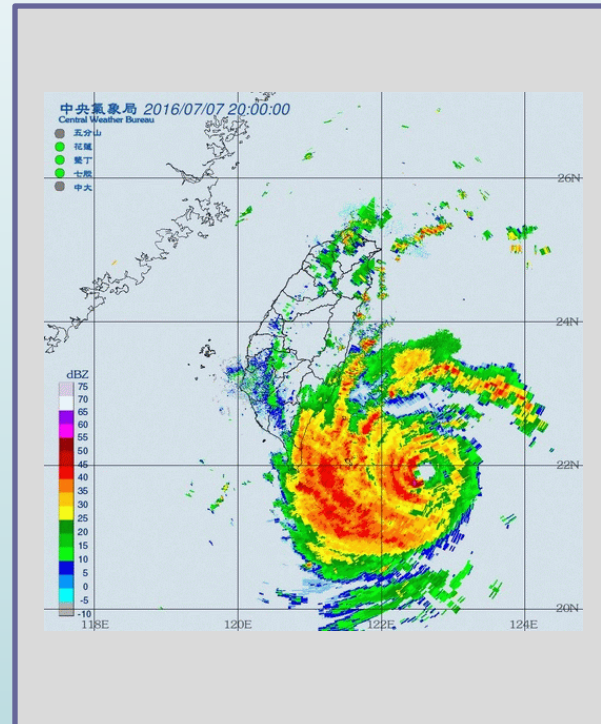
NWP need the knowledge among math, physics, computer science, statistics...



Sometimes miracle happened



Model forecast



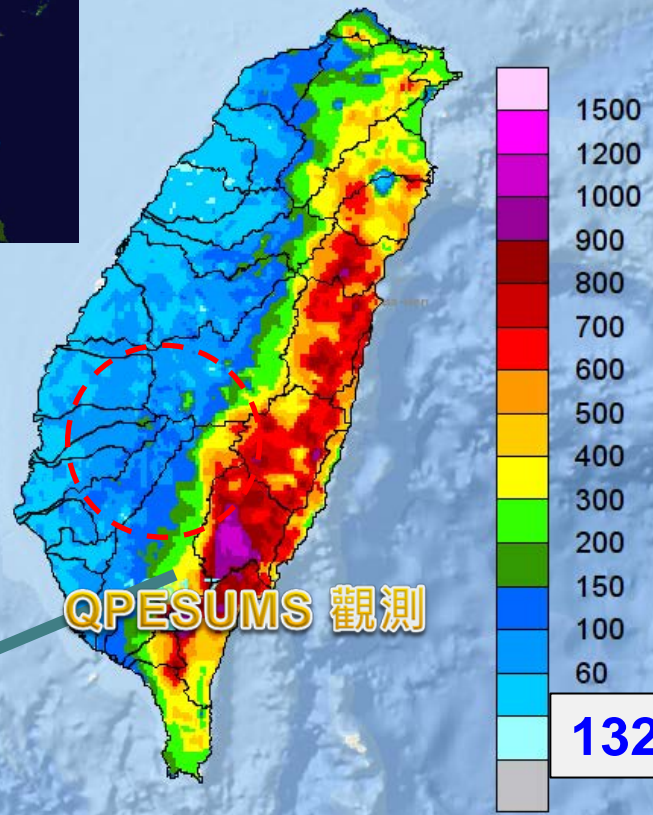
Radar observation

Almost reproduce the “Typhoon” in the MODEL

Initial at 2017101600 UTC

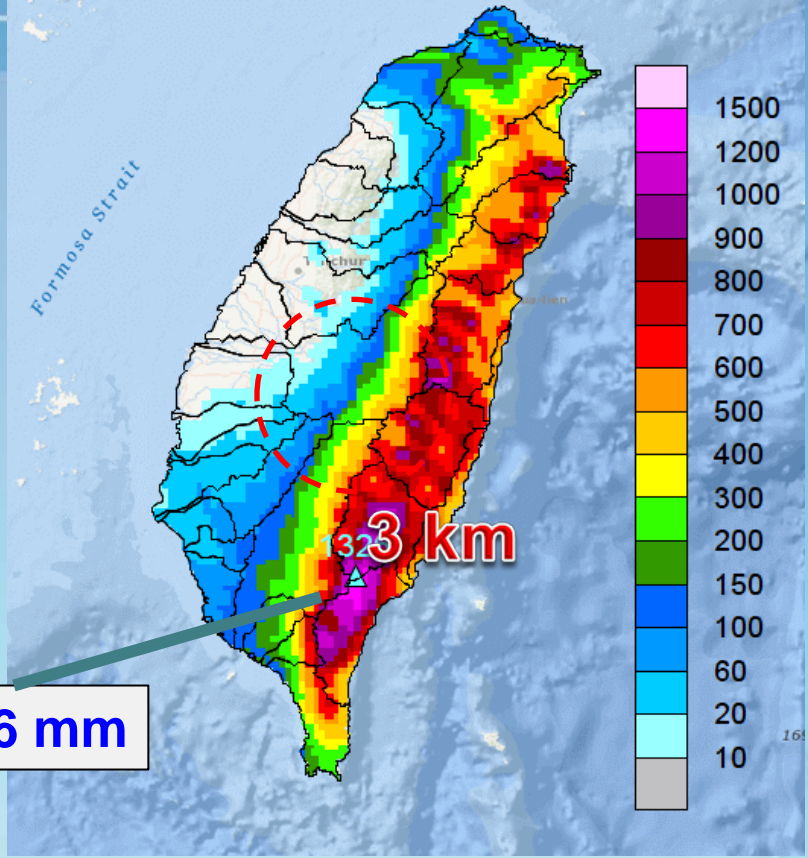


cum_072 QPESUMS_QPE @ 2017/10/16 08:00



1362 mm

cum_072 CWBWRP_M04 @ 2017/10/16 08:00



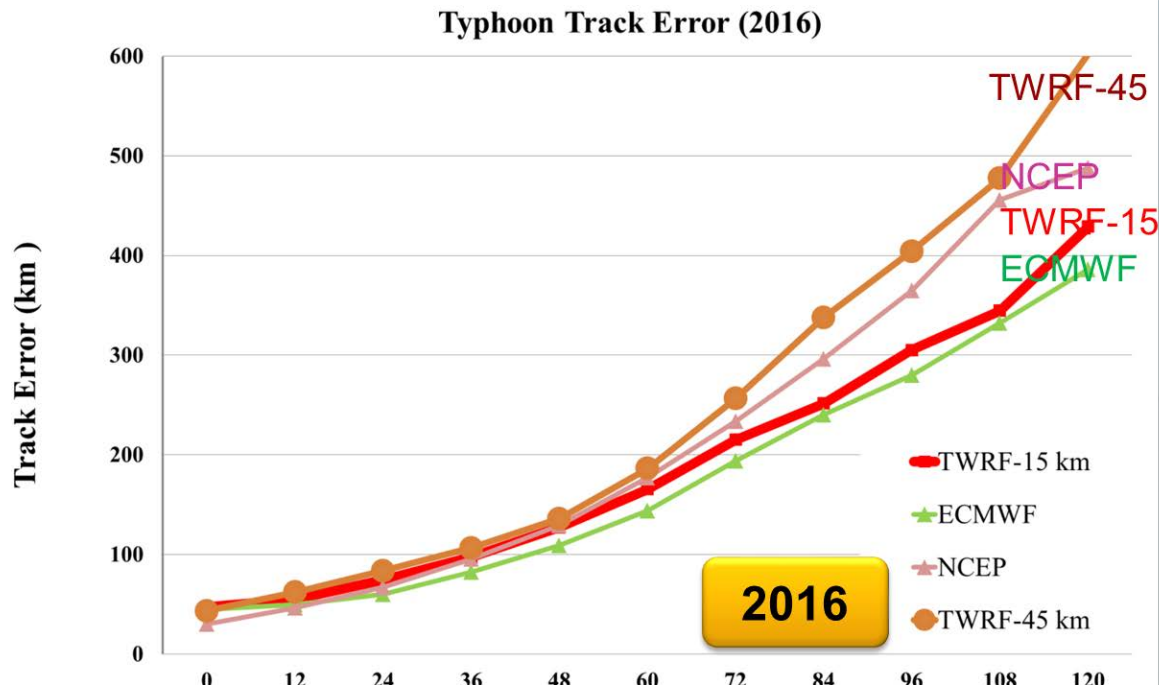
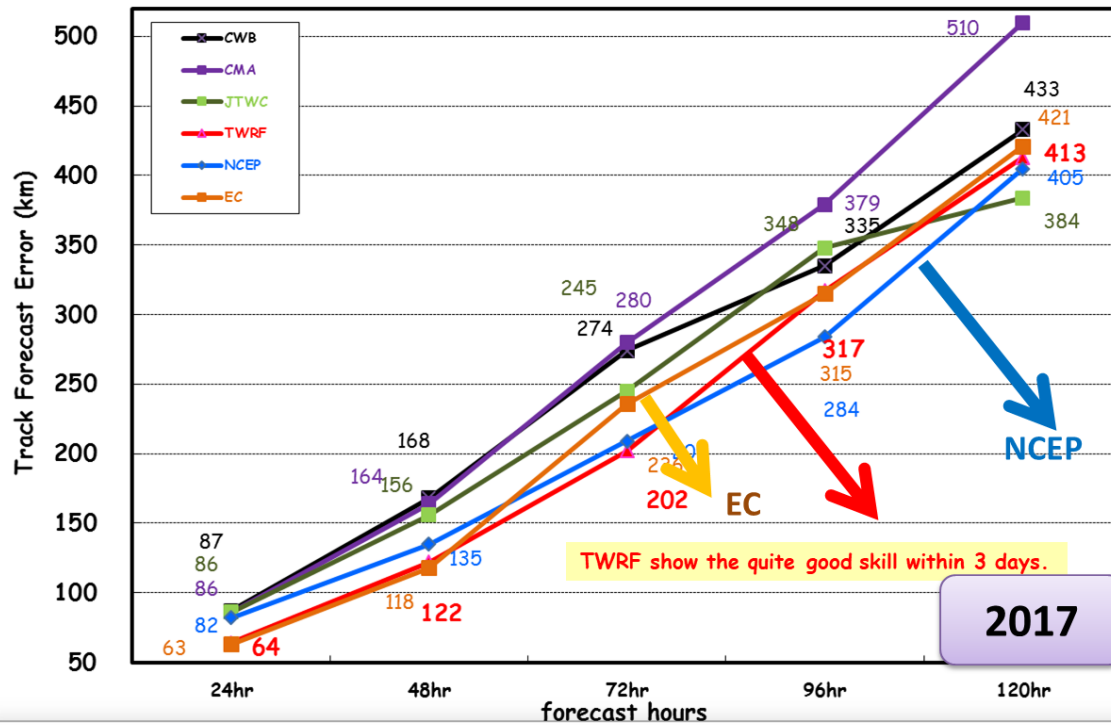
1326 mm

323 km

Typhoon Khanun related distant rainfall

3-day accumulated rainfall (多采公司繪圖)

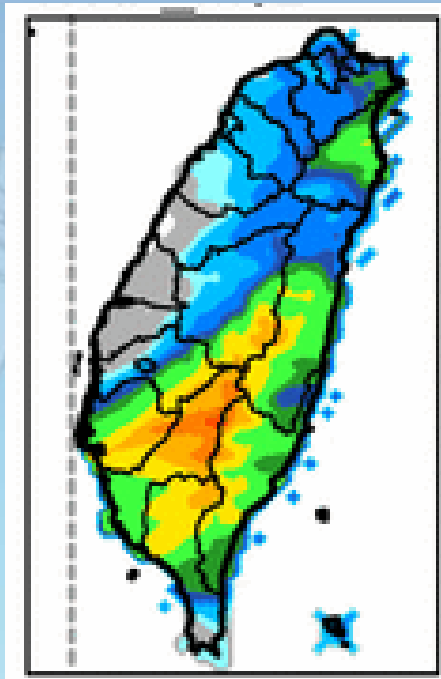
ChartDirector (unregistered) from www.advsofteng.com



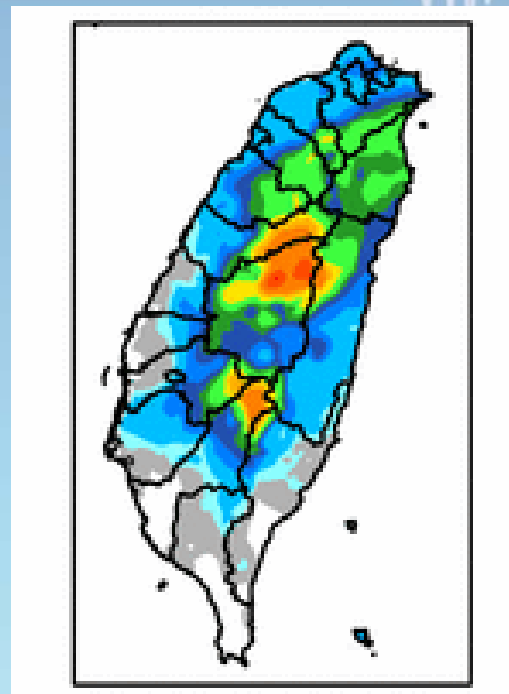
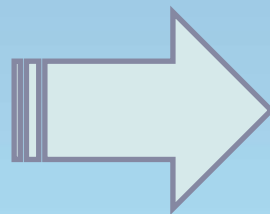


However

Does the model performs
so Perfect all the time?



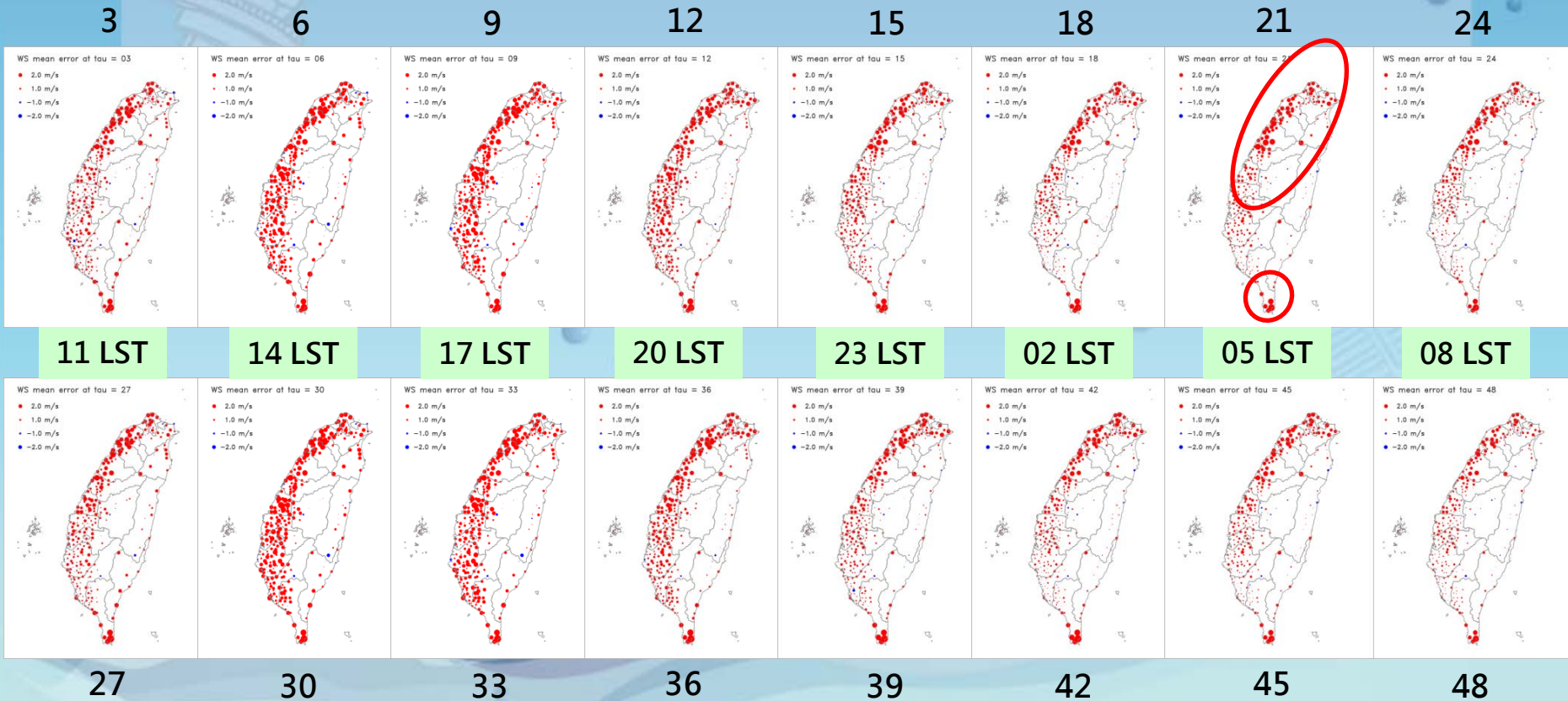
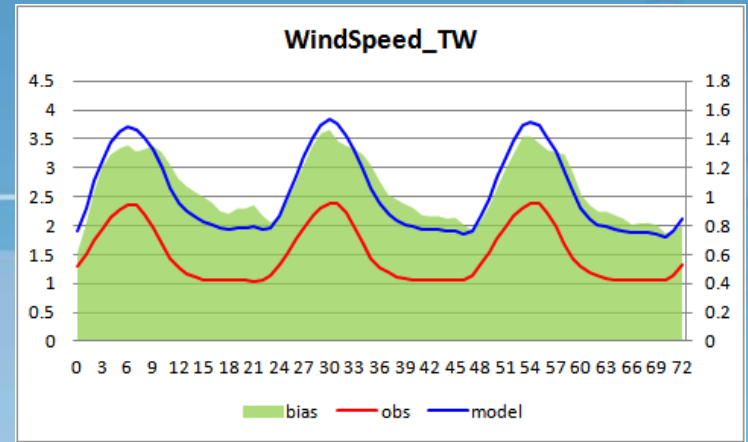
Model

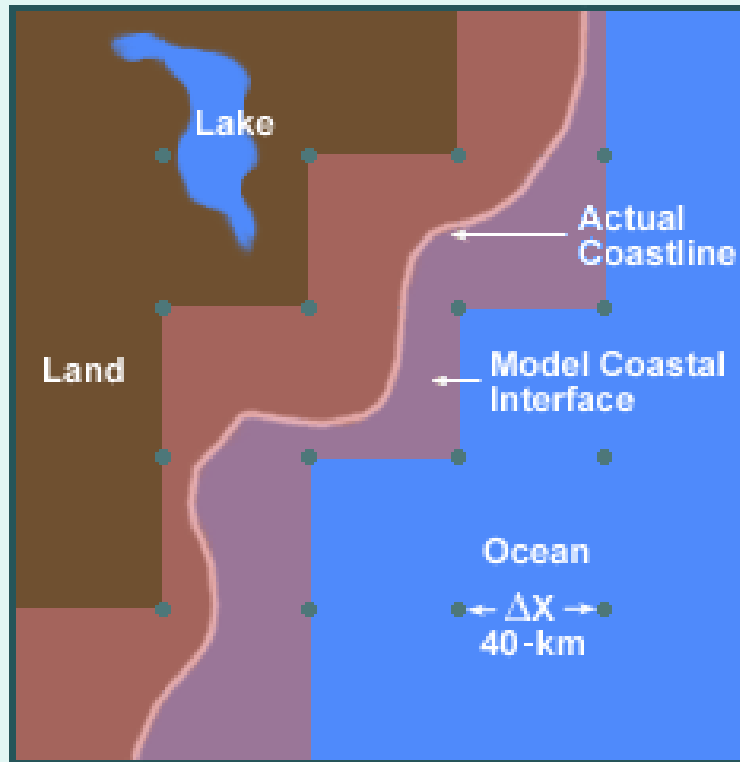


OBS

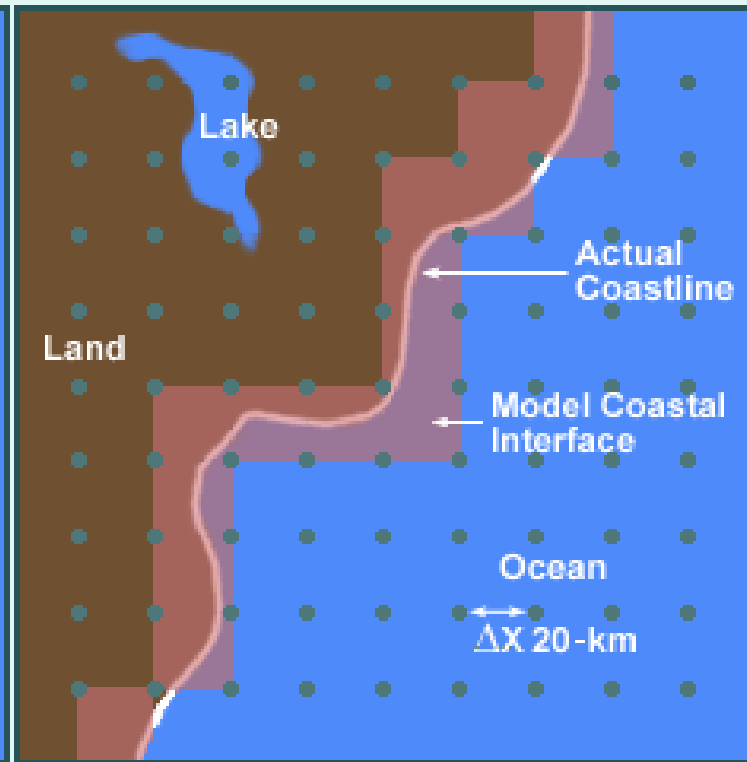


Wind speed prediction error





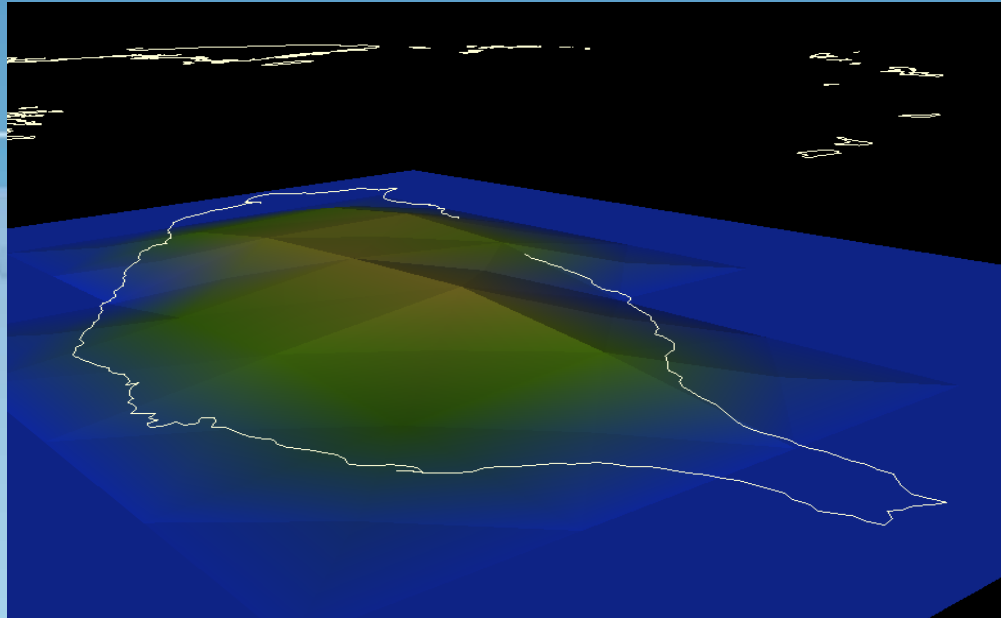
Model A: 40-km Resolution



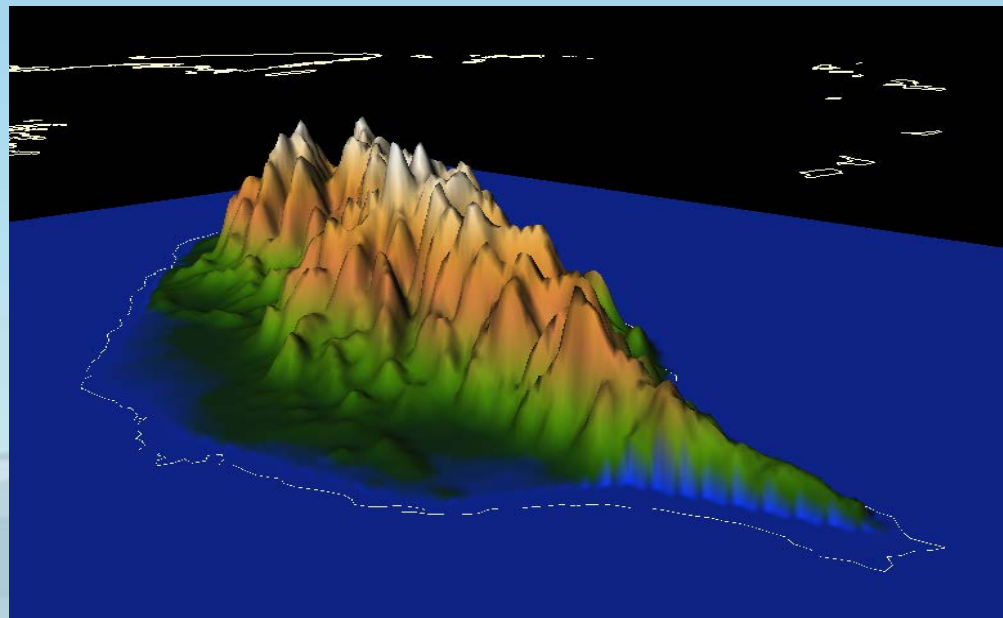
Model B: 20-km Resolution

Coastal Region within the Model

The COMET Program

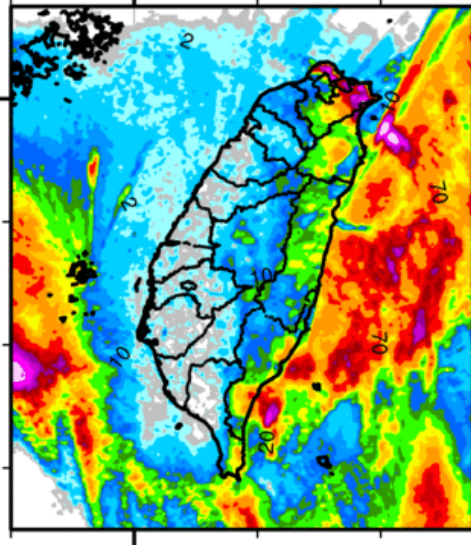


15-km resolution

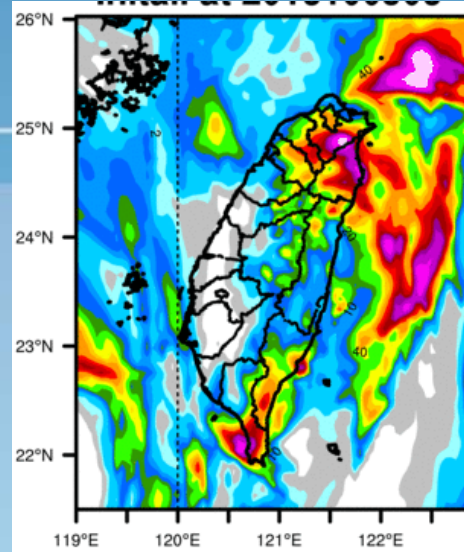


5-km resolution

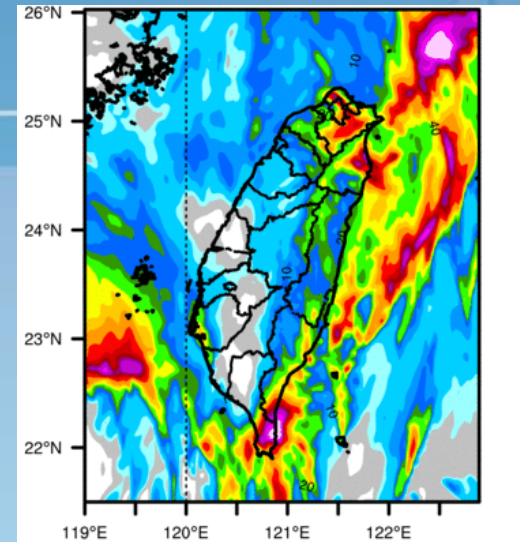
Observation



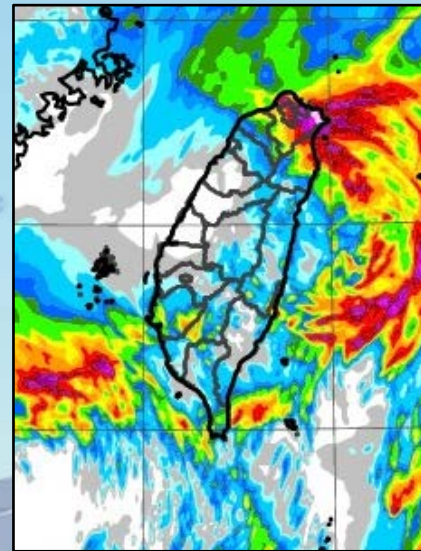
5 km



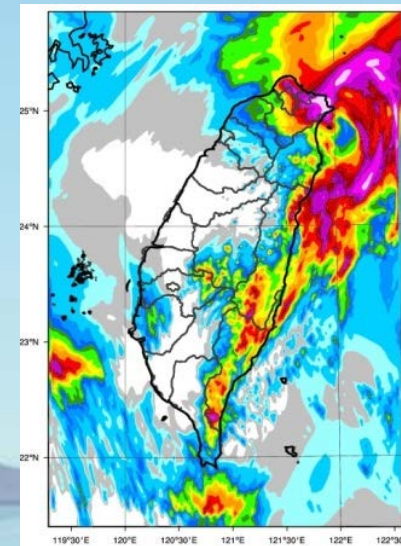
3 km



2 km



1 km

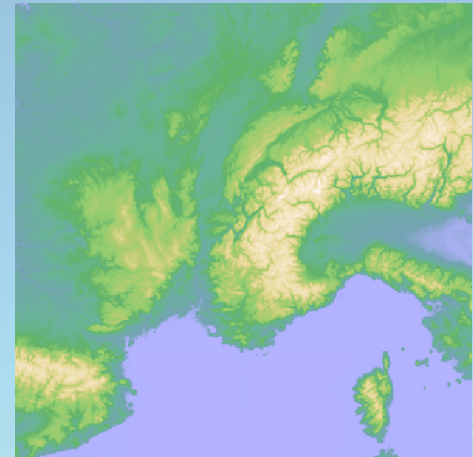
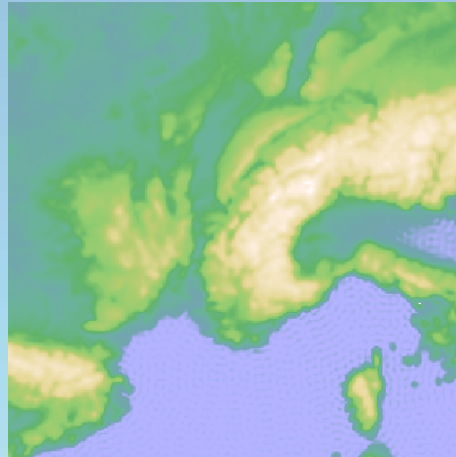
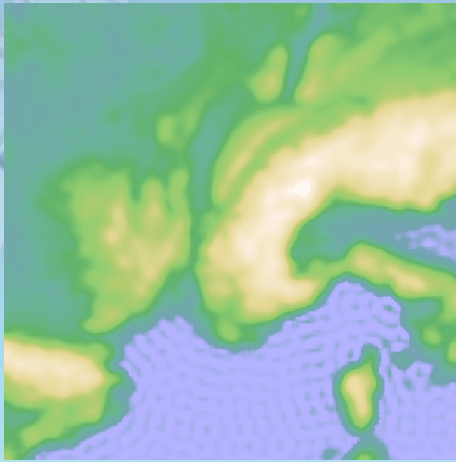


20161009 case



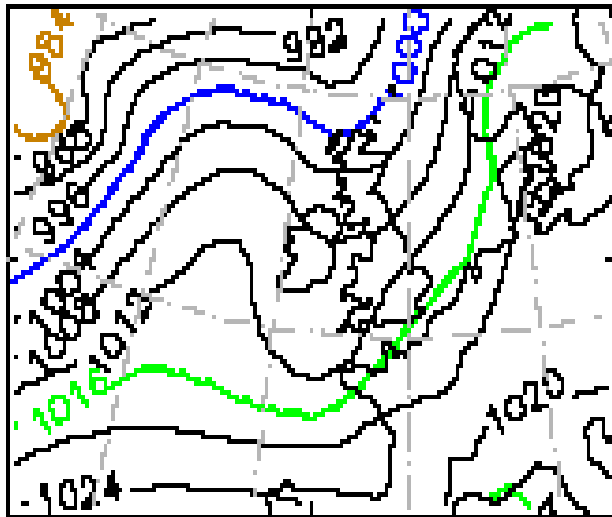
- The more details in the model, the better results.
- It means we need much more computer power

(A) 10 km resolution , (B) 5 km resolution , (C) 1.25 km resolution.

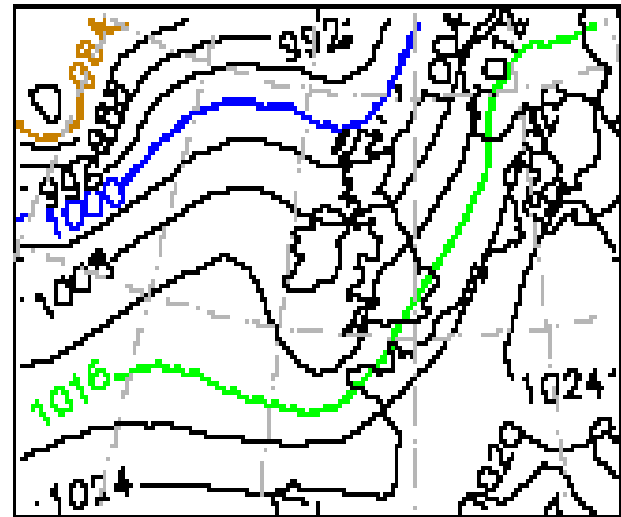


Resolution	1	2	8
Computing cost	1	8	512

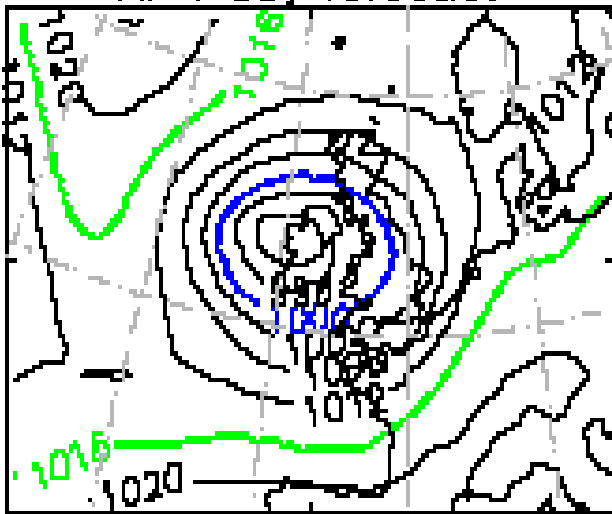
A: Start



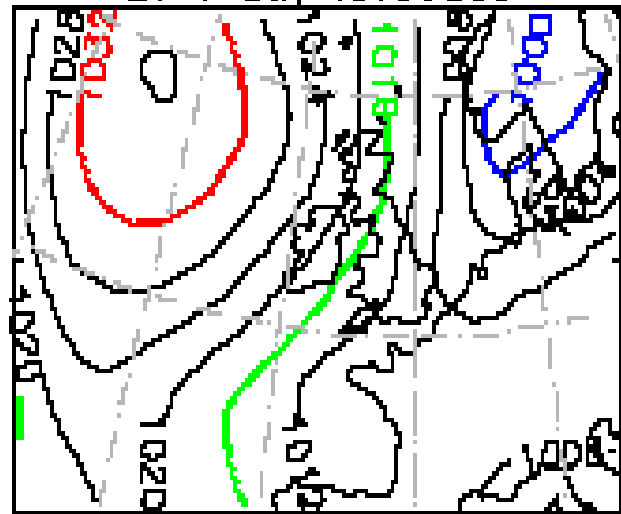
B: Start



A: 4 day forecast



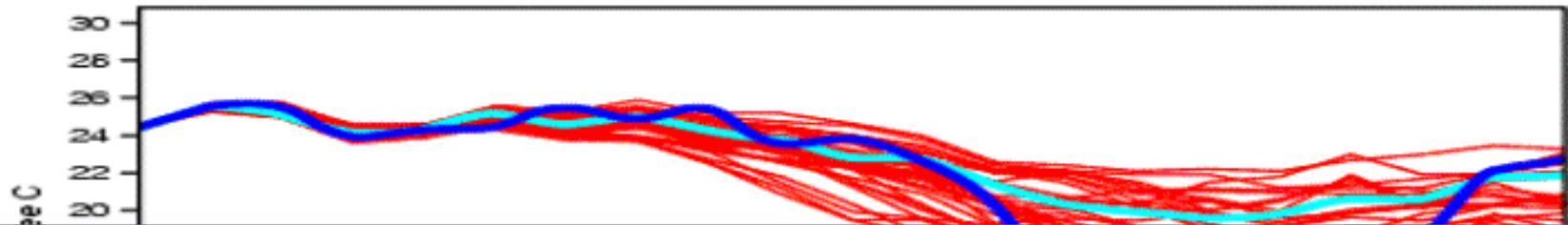
B: 4 day forecast



ECMWF ensemble forecast - Air temperature

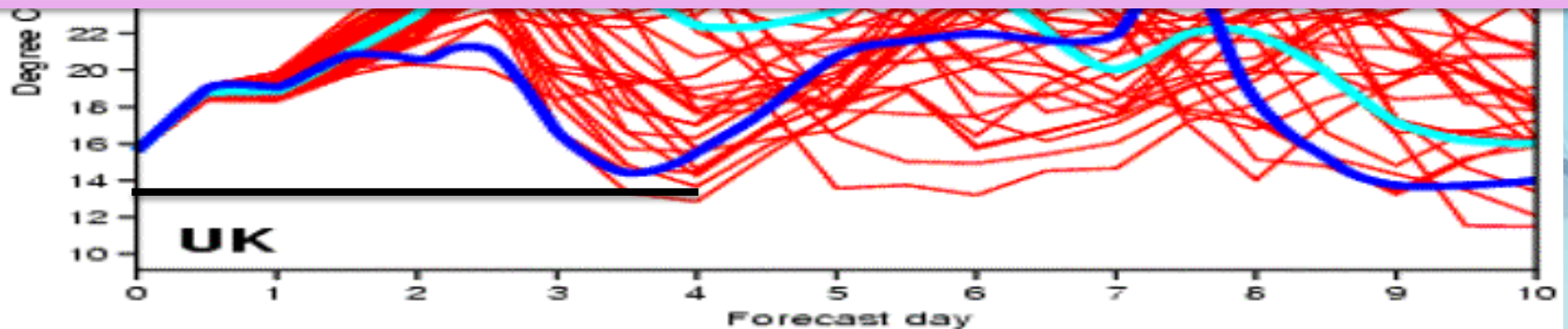
Date: 26/06/1995 London Lat: 51.5 Long: 0

Control Analysis Ensemble



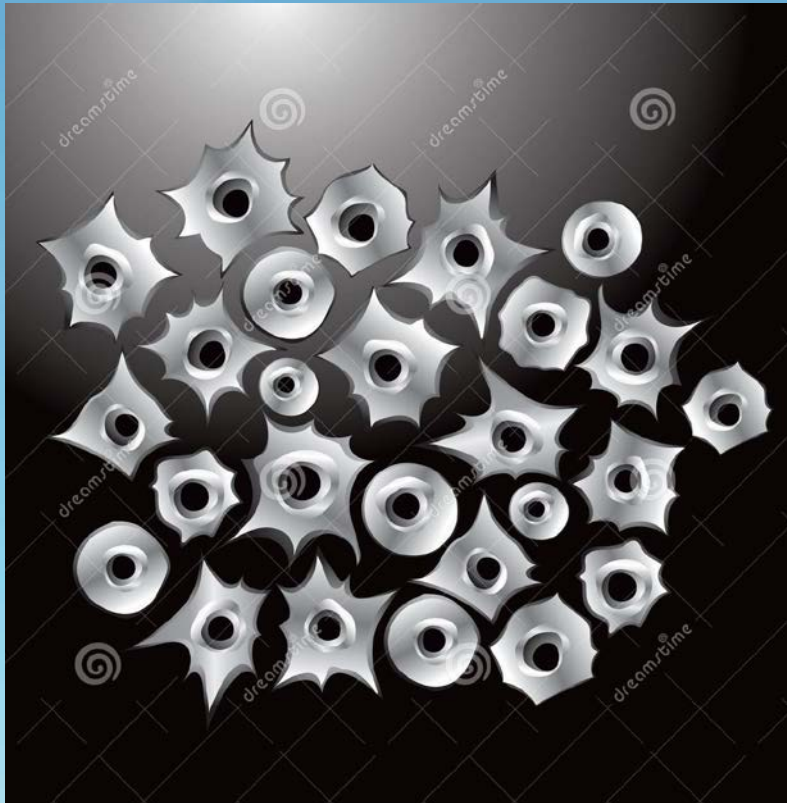
- The **uncertainty** may be the NATURE of fluid system.
- The model process from, e.g. the mathematics, physical process, numeric, and initial condition could introduce the un-controllable uncertainties.

What can we do?



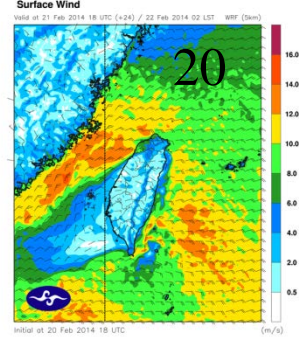
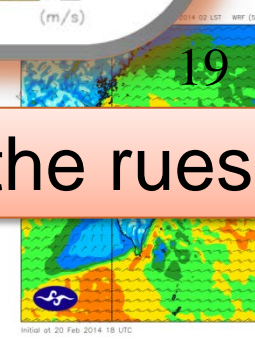
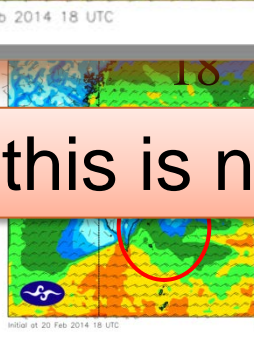
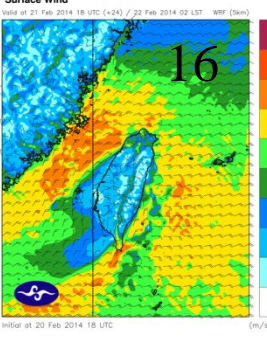
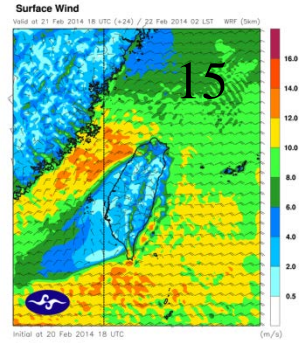
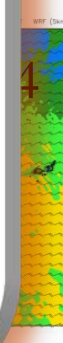
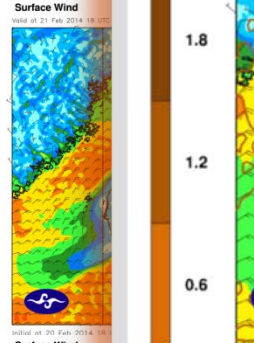
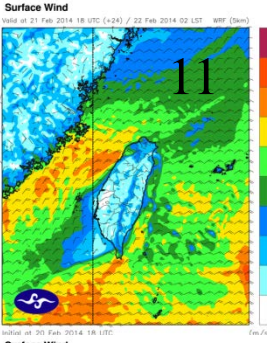
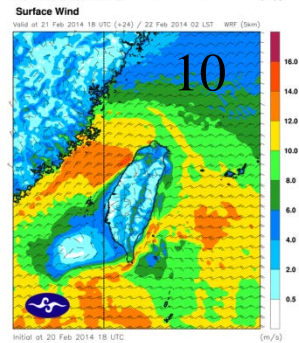
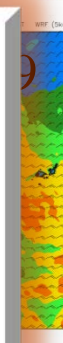
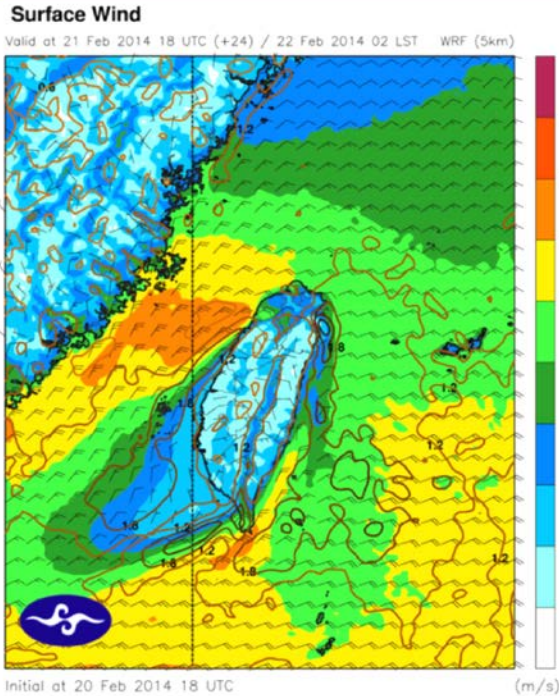
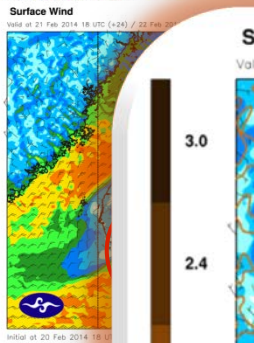
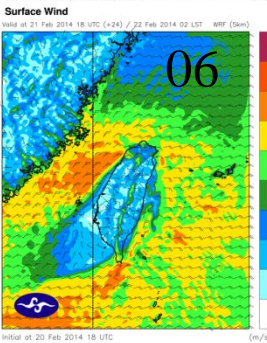
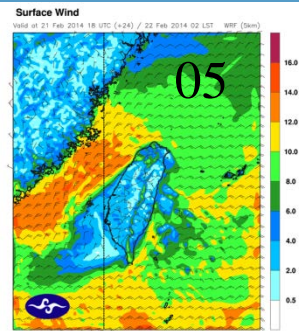
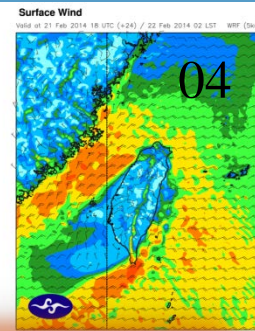
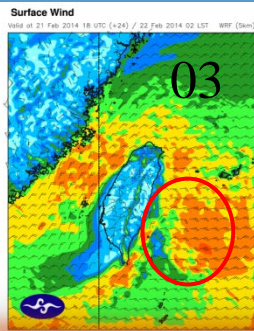
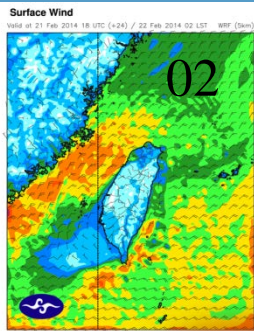
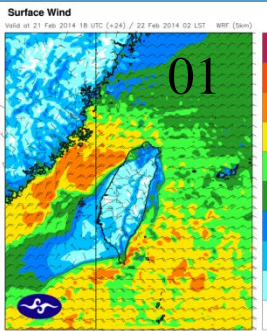


A single (deterministic) model behaves like a sniper rifle

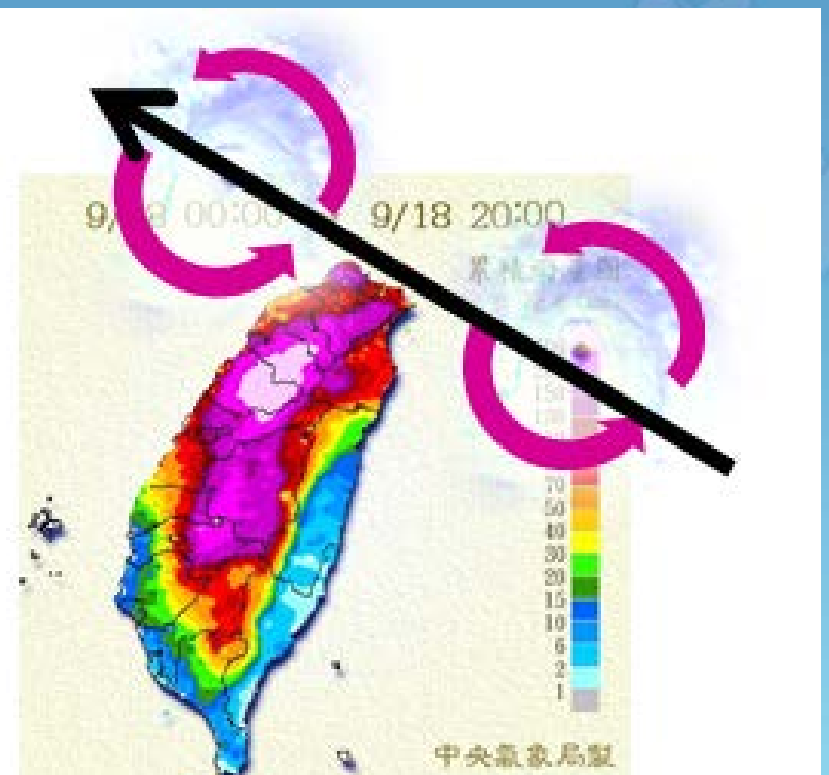
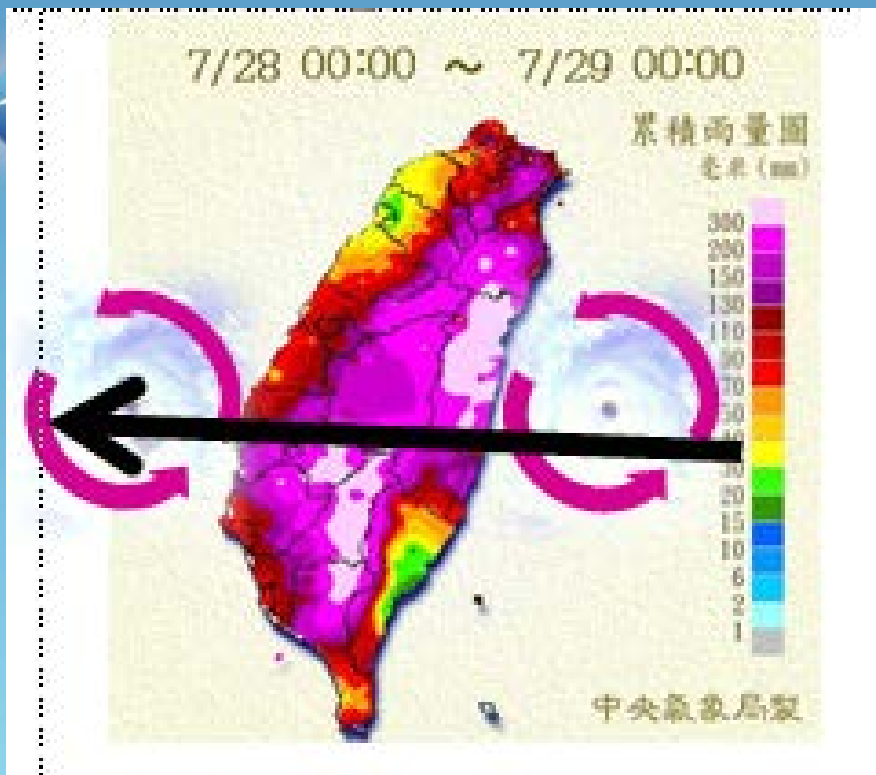


How about a shotgun?

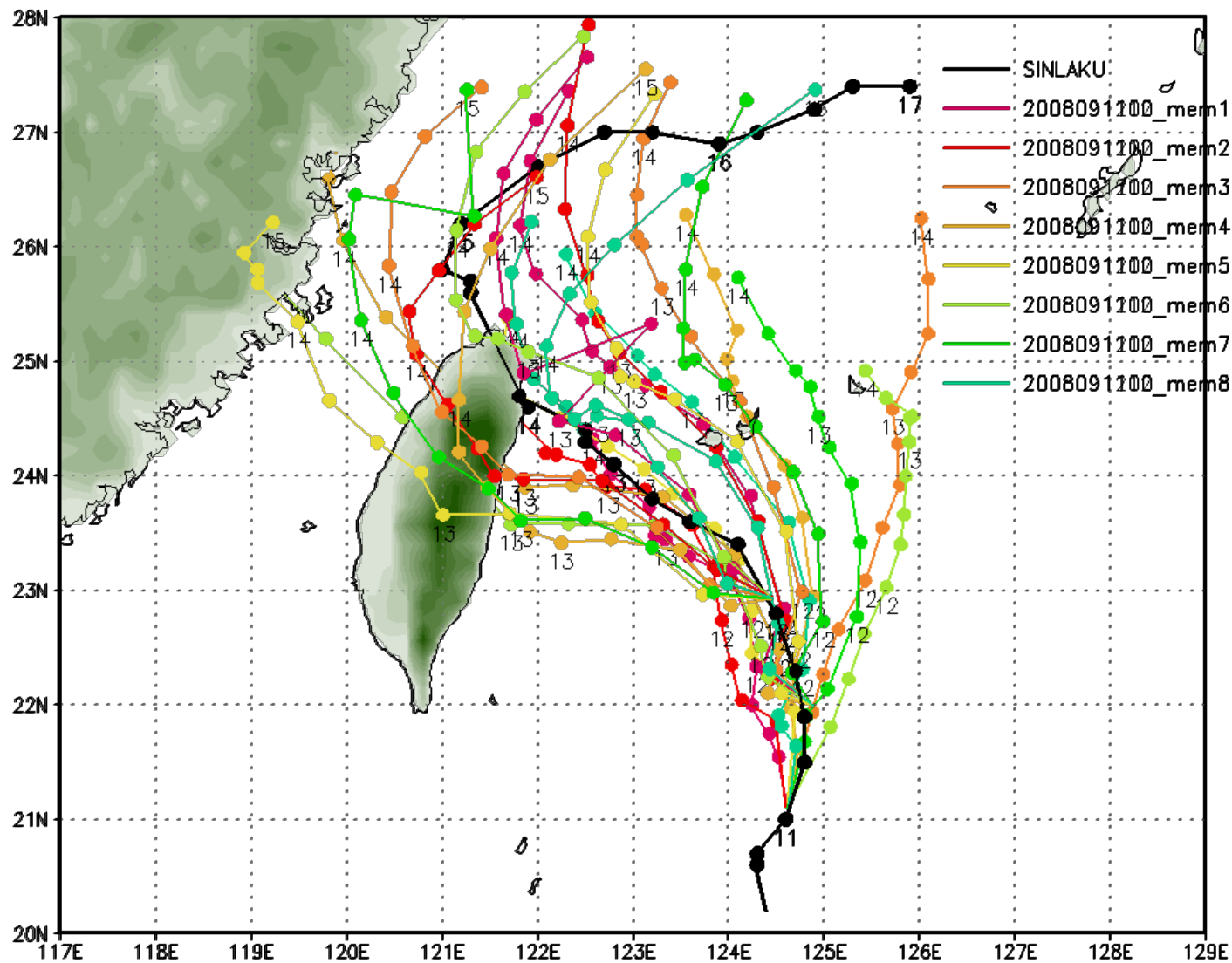
**Toward to the ensemble forecast
(系集預報)**



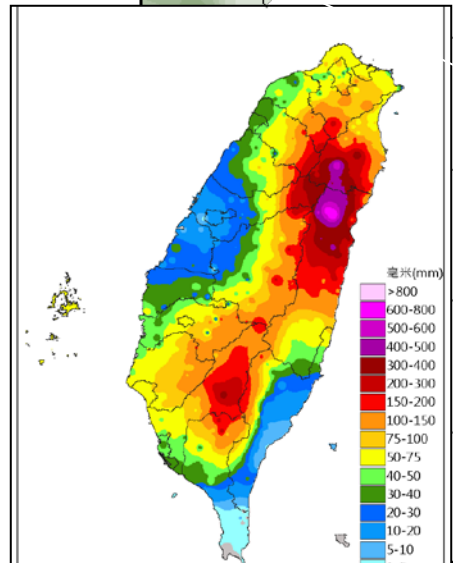
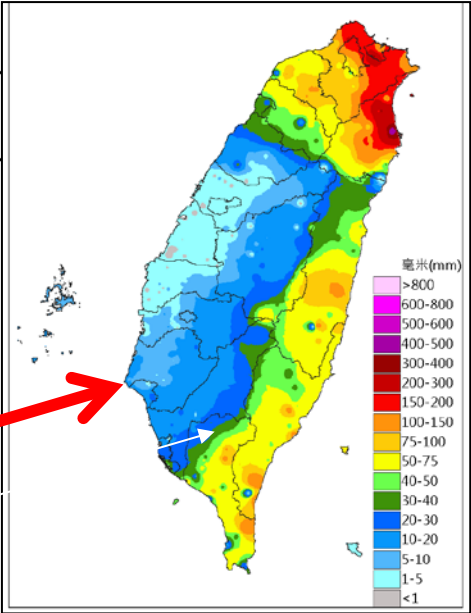
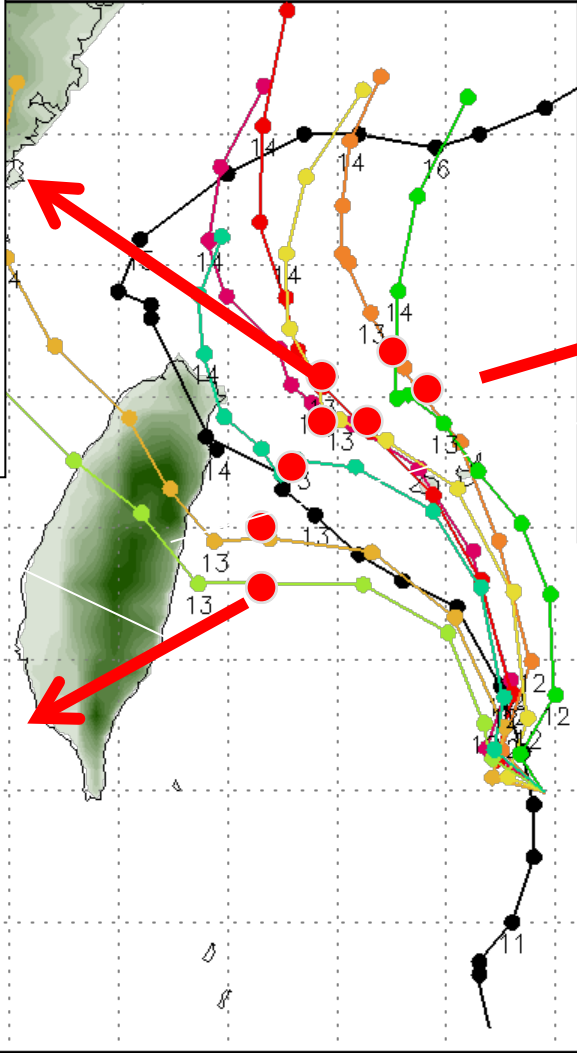
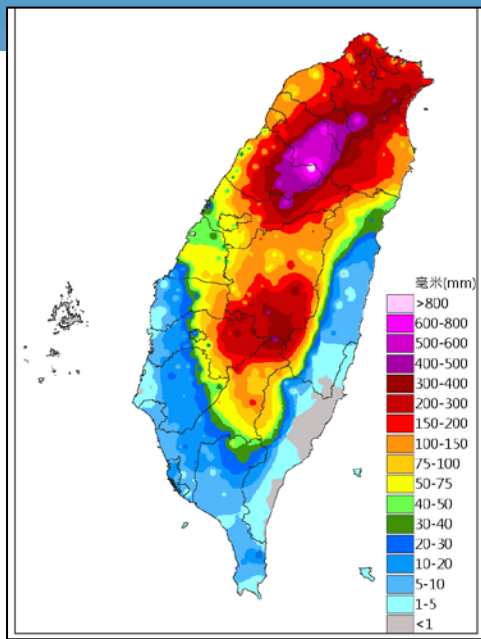
However, this is not the rues



Terrain locking effect



What can we do to extract the useful model
 TY QPF information from ensemble forecast?



Take the ensemble mean? Weighted over the members?
 “Mean” is not always a good idea

Application of the probability products

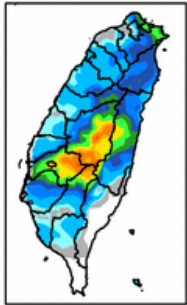


initail at 0000 UTC 05 May 2014

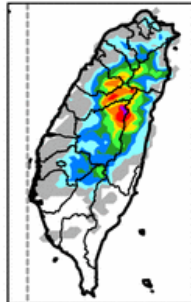
12~24hr fcst Accumulated rainfall from 2014050512 ~ 2014050600

Probability exceeding rainfall threshold

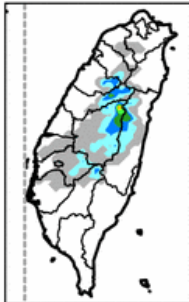
OBS



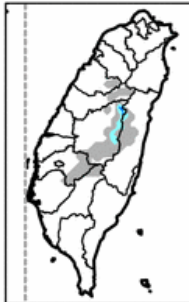
threshold= 25 mm



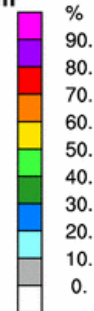
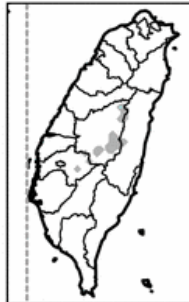
threshold= 50 mm



threshold= 75 mm



threshold= 100 mm

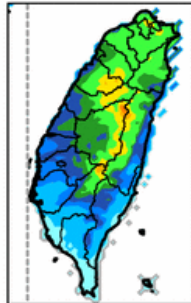


initail at 0000 UTC 06 May 2014

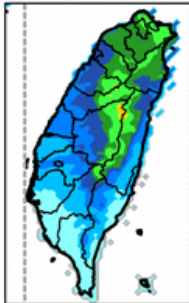
00~12hr fcst Accumulated rainfall from 2014050600 ~ 2014050612

QPF exceeding probability threshold

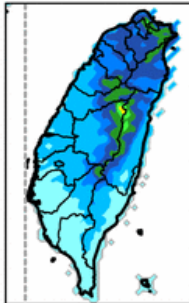
Percentile= 20%



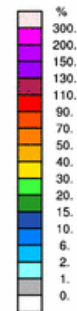
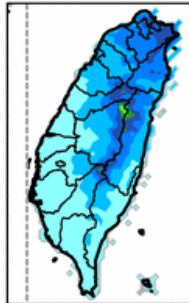
Percentile= 40%



Percentile= 60%



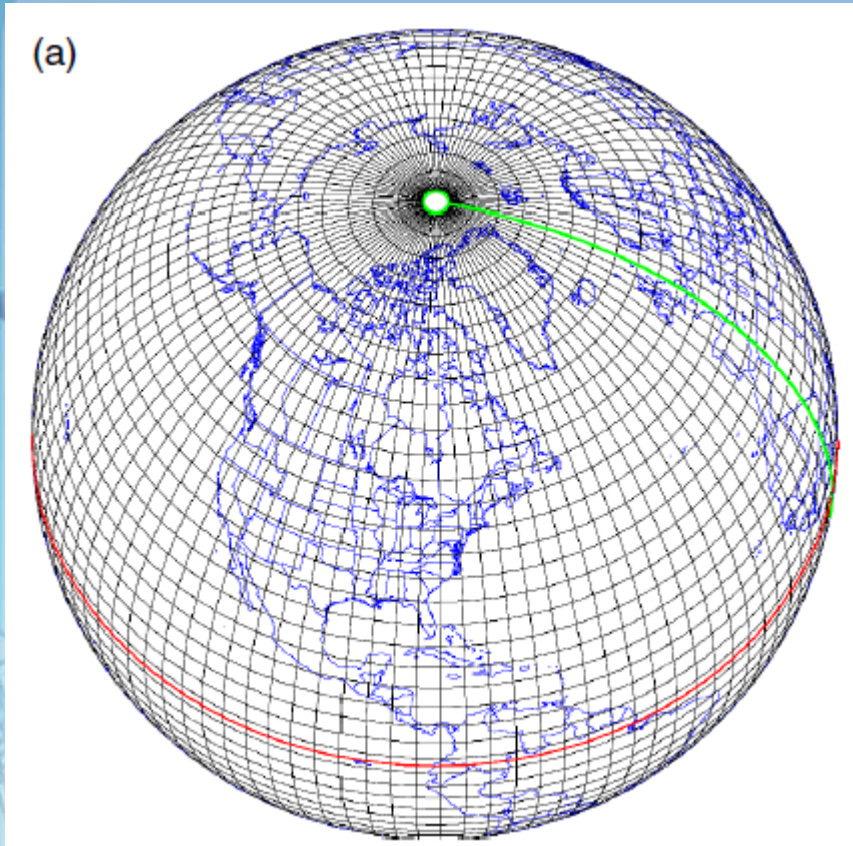
Percentile= 80%



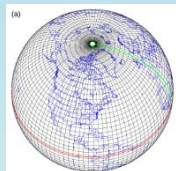
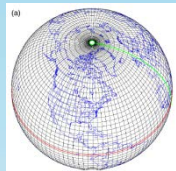
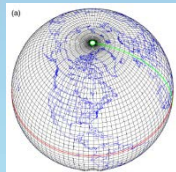
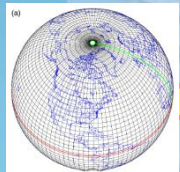
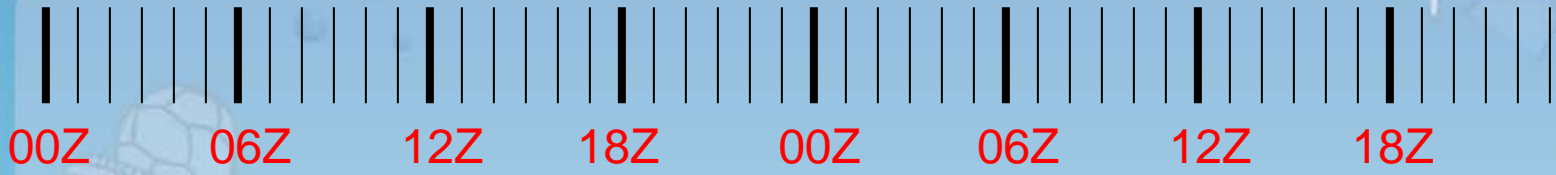


因應對策：

- **引進大數據分析技術，提高負載/再生能源預測準確度**
- **日前預測分析技術：**
未來七天 (For Day-Ahead SCUC、SCED、Ancillary Service)
- **即時預測分析技術：**
未來 3~4 小時 (For Real-Time SCED、Ancillary Service)
每5或15分鐘 (For Real-Time Regulation & Spinning Reserve)



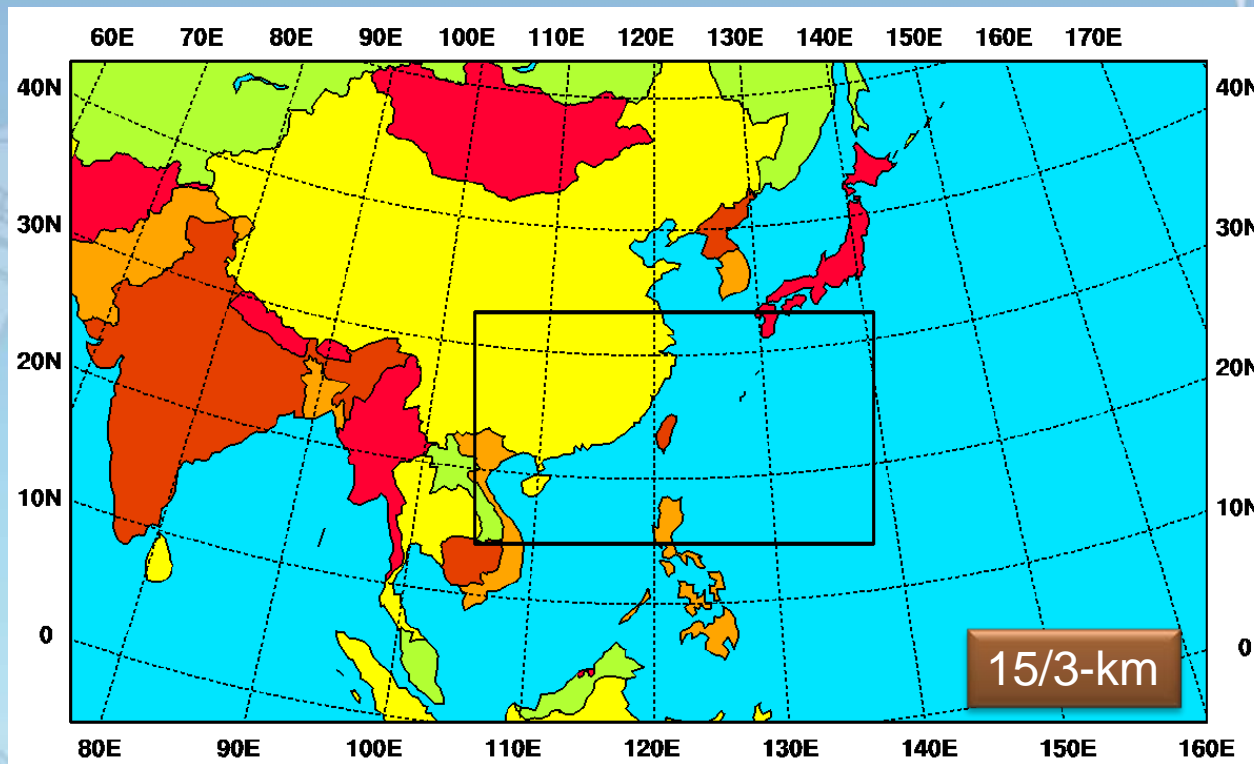
- ~25 km horizontal resolution
- Updated 4 times per day
- 6-Hourly output, extended to 14 days



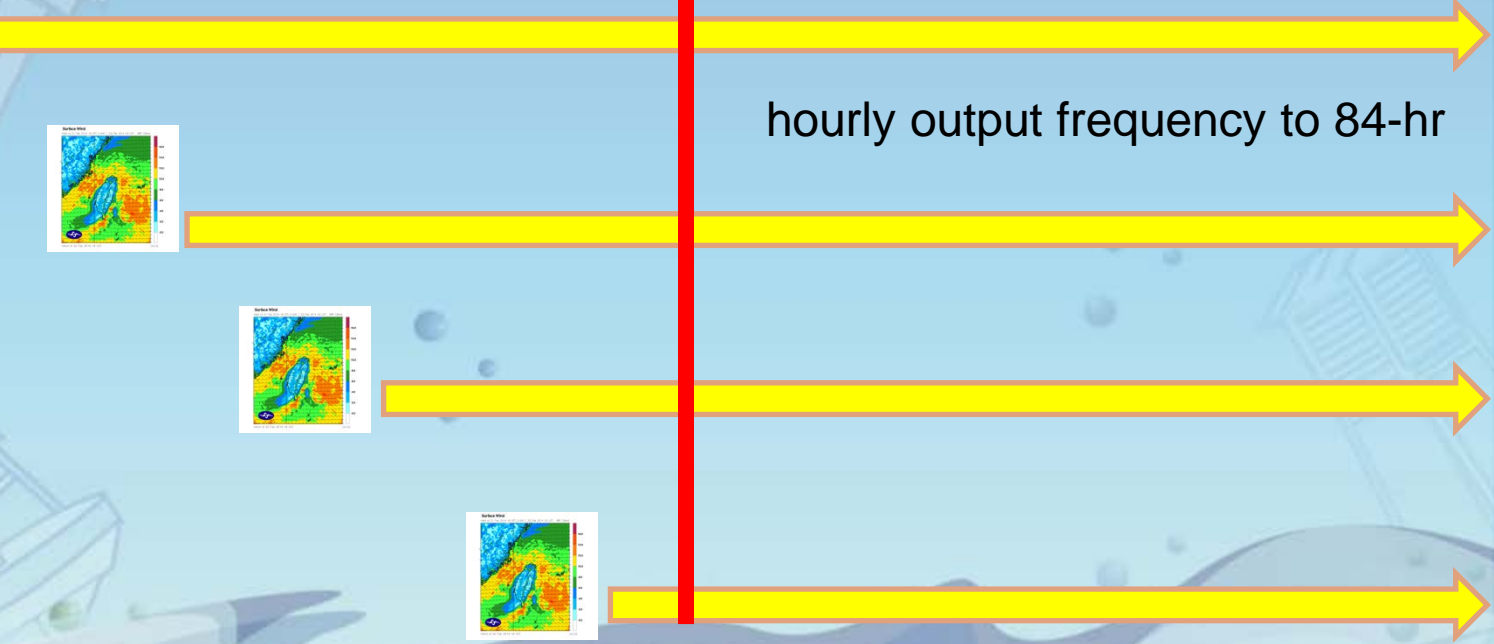
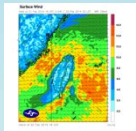
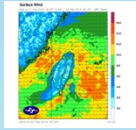
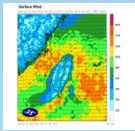
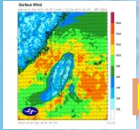
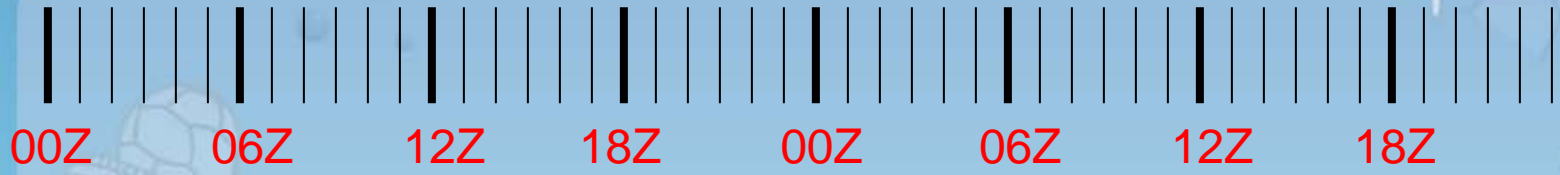
6-hr output frequency to 14 days



Deterministic model system

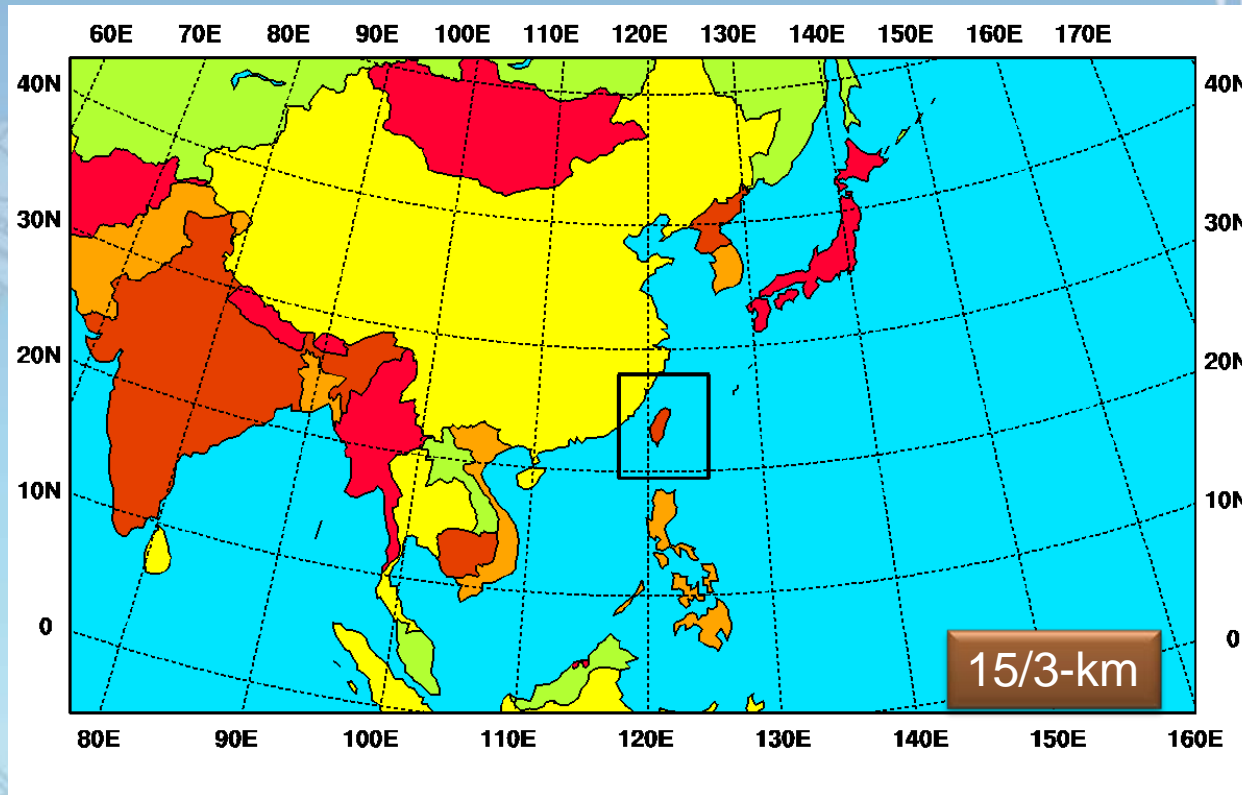


- 15/3 km horizontal resolution
- Updated 4 times per day
- Hourly output, extended to 84 hour

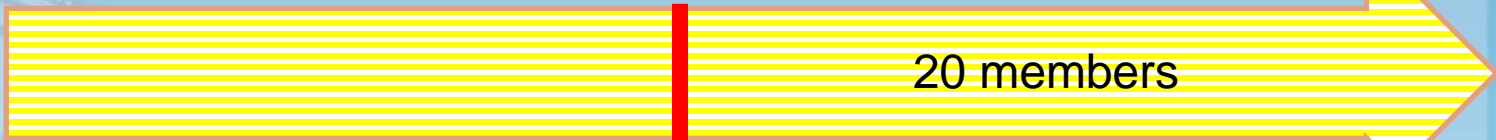
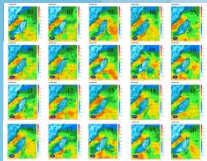
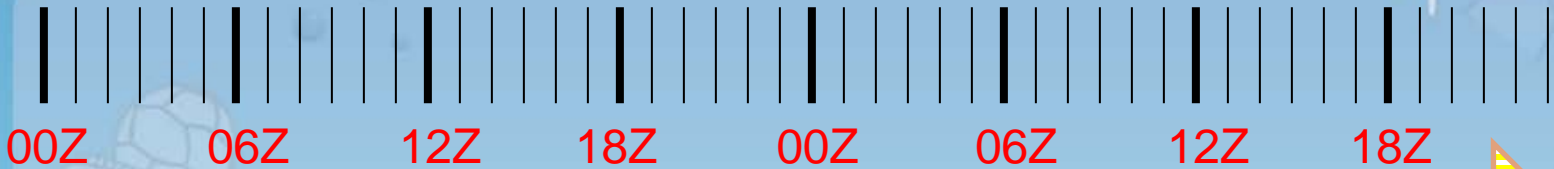




Ensemble model system

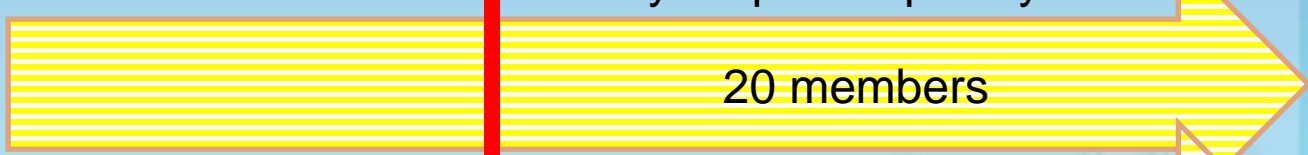
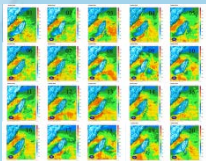


- 15/3 km horizontal resolution
- Updated 4 times per day, **20 members per run**
- Hourly output, extended to 84 hour

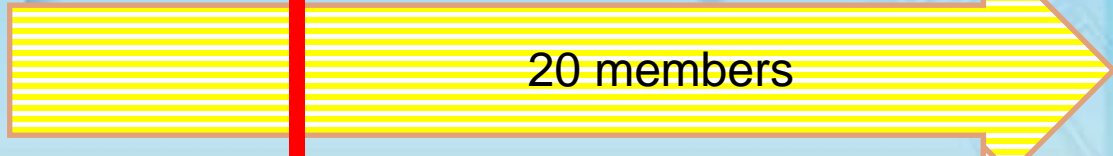
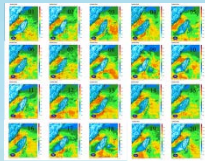


20 members

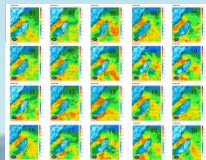
hourly output frequency to 84-hr



20 members



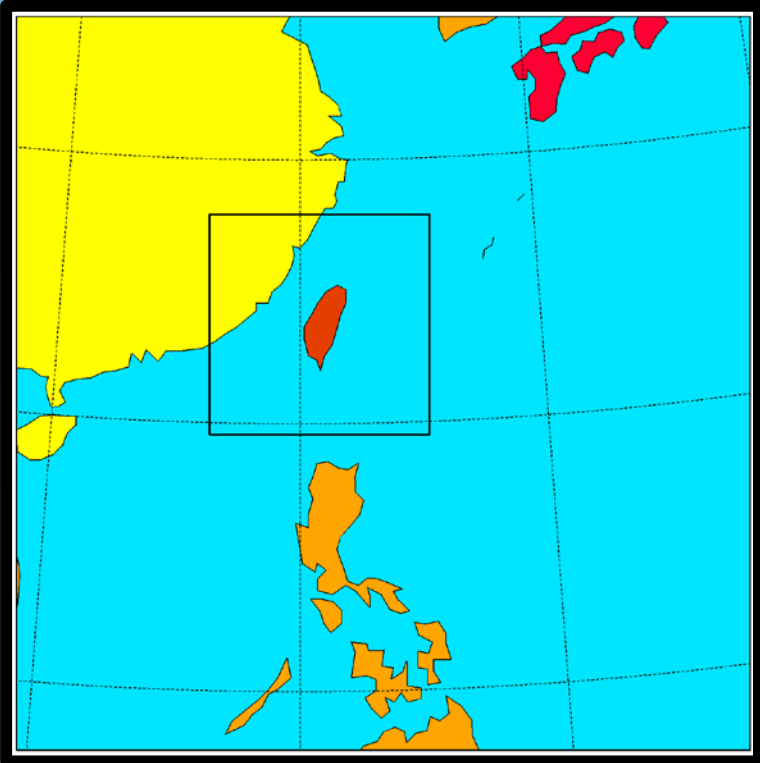
20 members



20 members



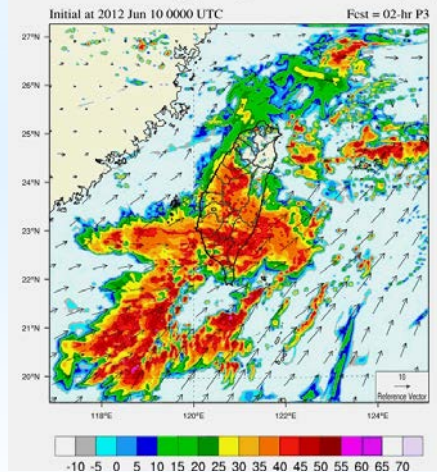
Convective scale nowcasting



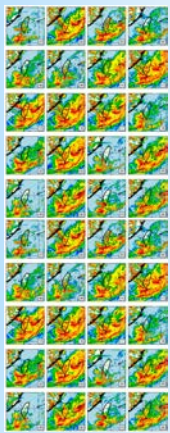
- 10-km/2-km Domain
 - Convective scale DA, assimilate the Taiwan local observations, especially for the radar observation
 - hourly updated (24 times per day)
 - Hourly output, extended to 12-hr forecast



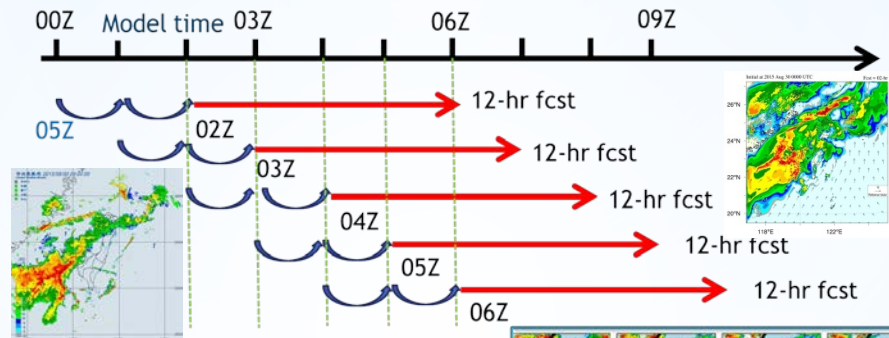
Max reflectivity(dBZ) / Wind Vector(m/s)



Hybrid 3DEnVAR



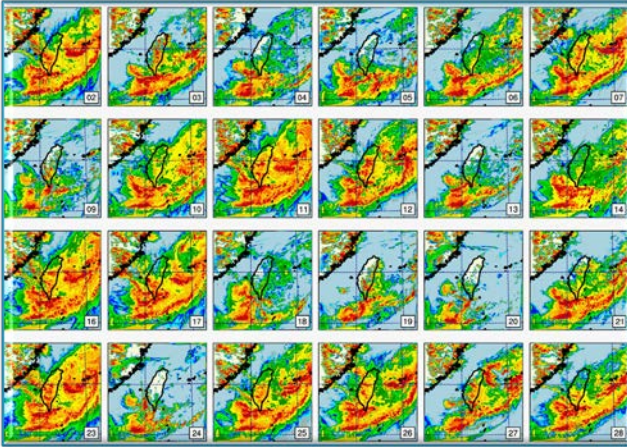
LETKF
In 2017



Realtime, hourly updated system extended to 24-hr forecast

Radar and all available observations

Convective scale EPS



Convective scale QPN at 2-km resolution

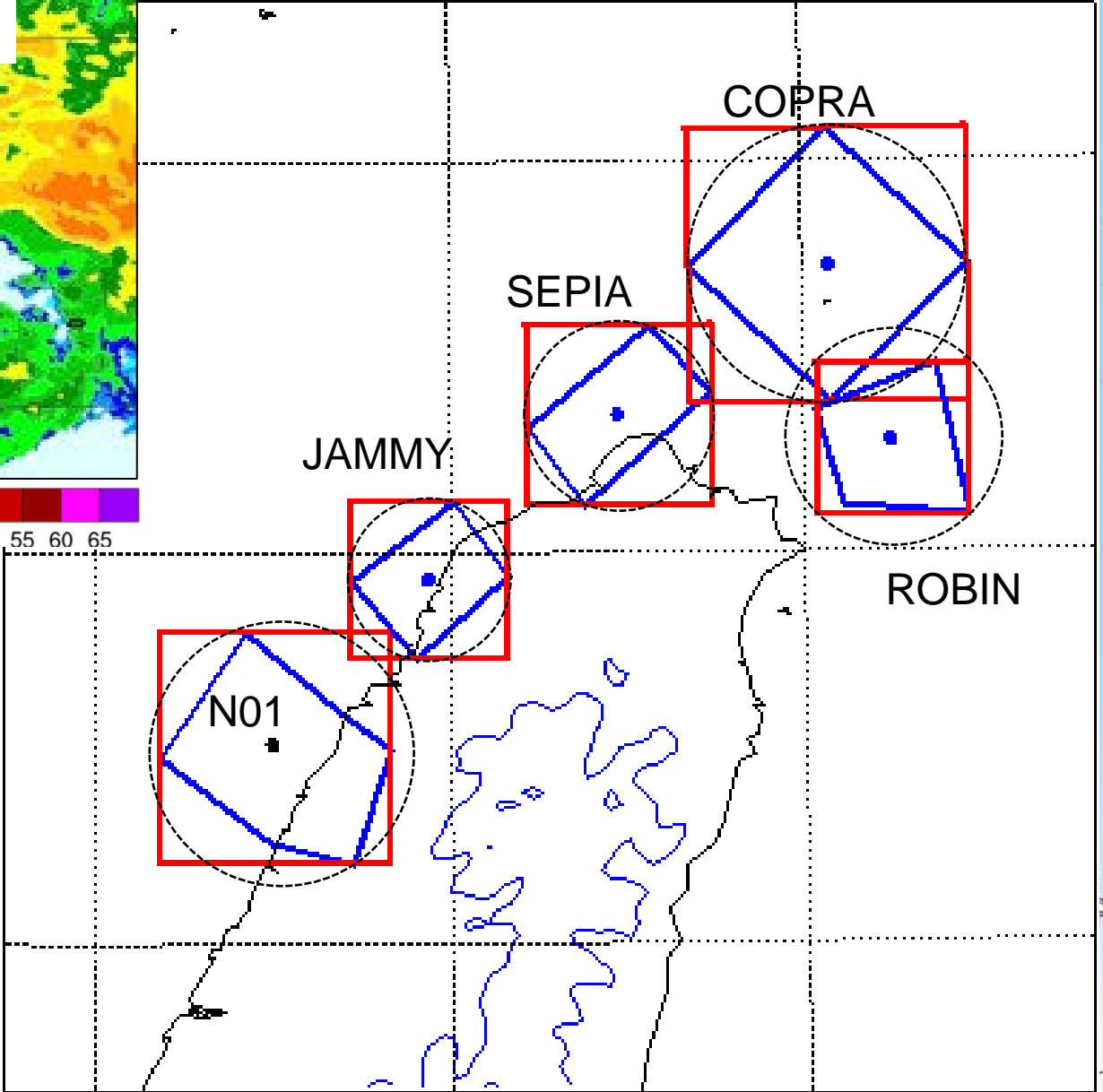
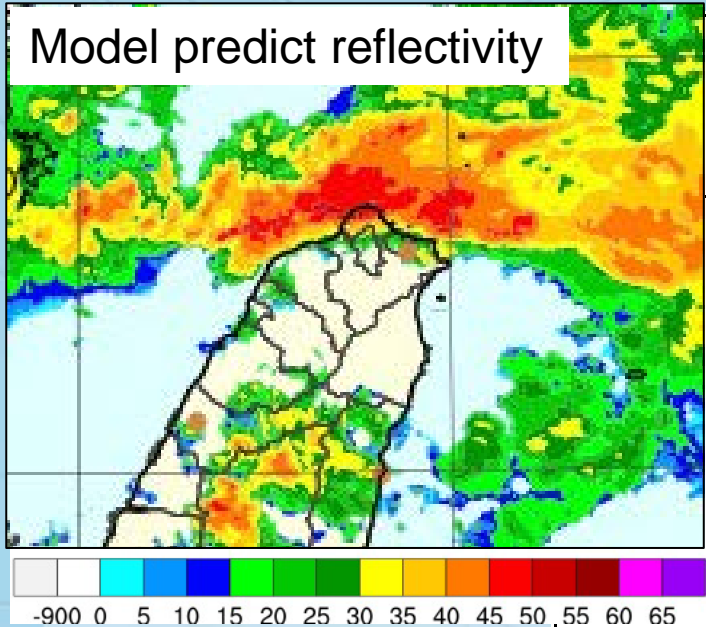


Applications

☀️ **CWB NWP model output provides services in all aspects**

- ✿ Hydrology, Flooding, and mudslide
- ✿ Air quality prediction
- ✿ Aviation services
- ✿ Ocean current and wave
- ✿ Search and Rescue Planning
- ✿ Disaster prevention and decision making
- ✿ ...

Air traffic control



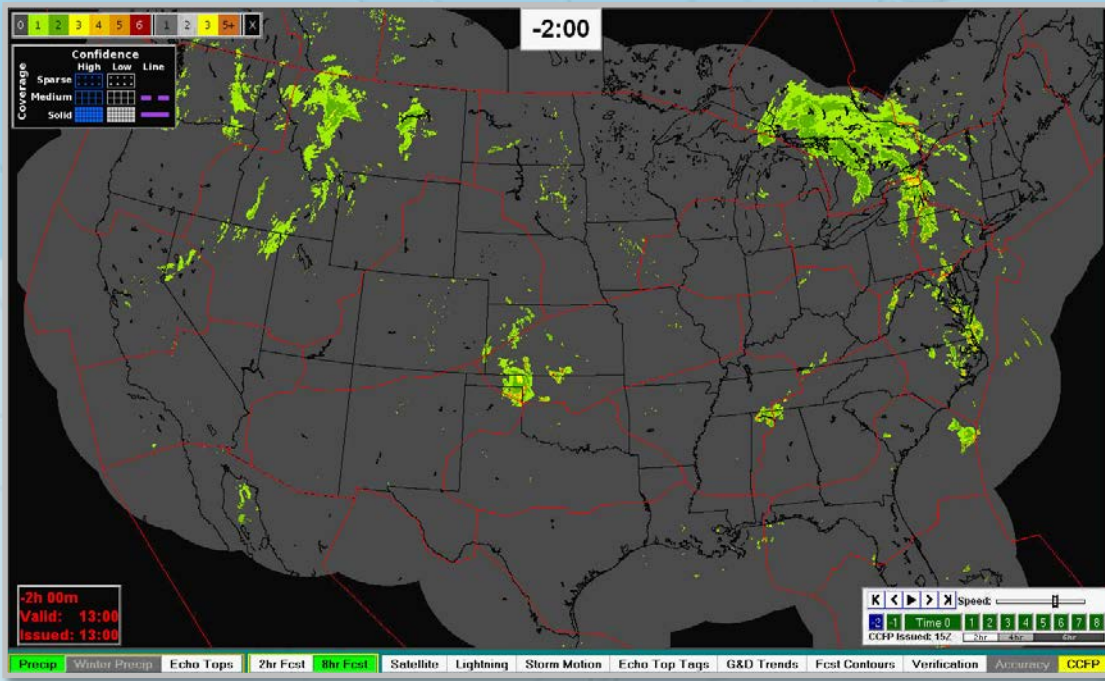


待命區	即時回波警示	17060404	17060405	17060406	17060407	17060408
N01	●				● ●	
JAMMY			● ● ●			● ●
SEPIA	●	● ●			●	
COPRA		● ●			●	● ●
ROBIN			● ●			● ● ●

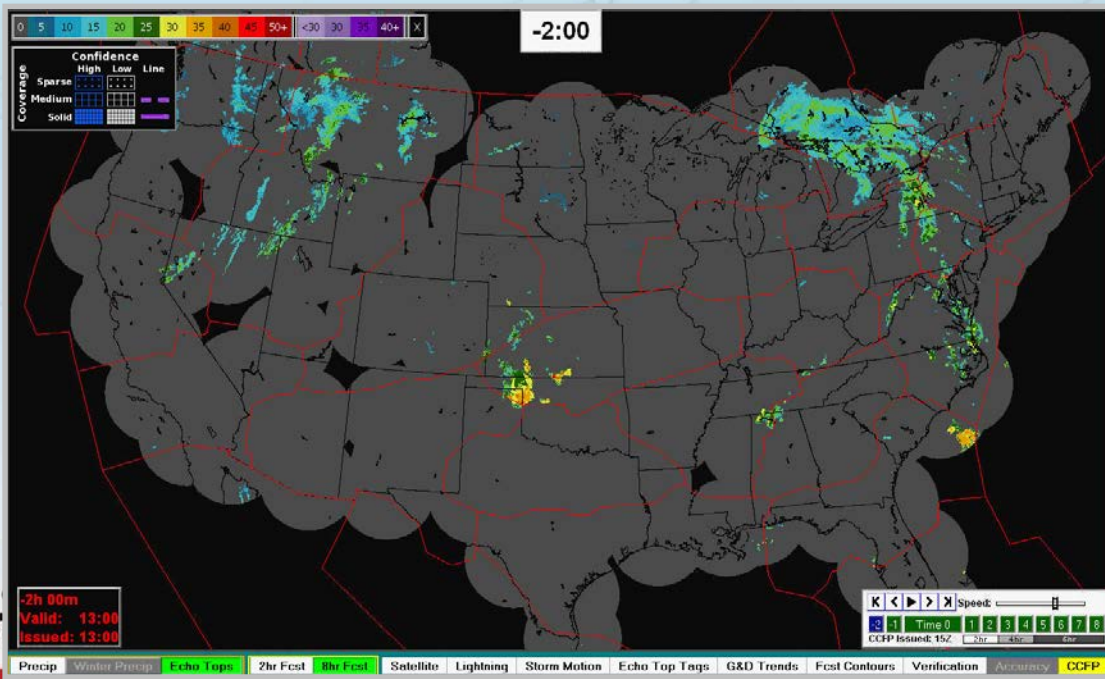
流域管制警示 (含過去三個預報報資訊)

- : 最新預報達警示標準
- : 前1報預報達警示標準
- : 前第2報預報達警示標準





降水



雲頂

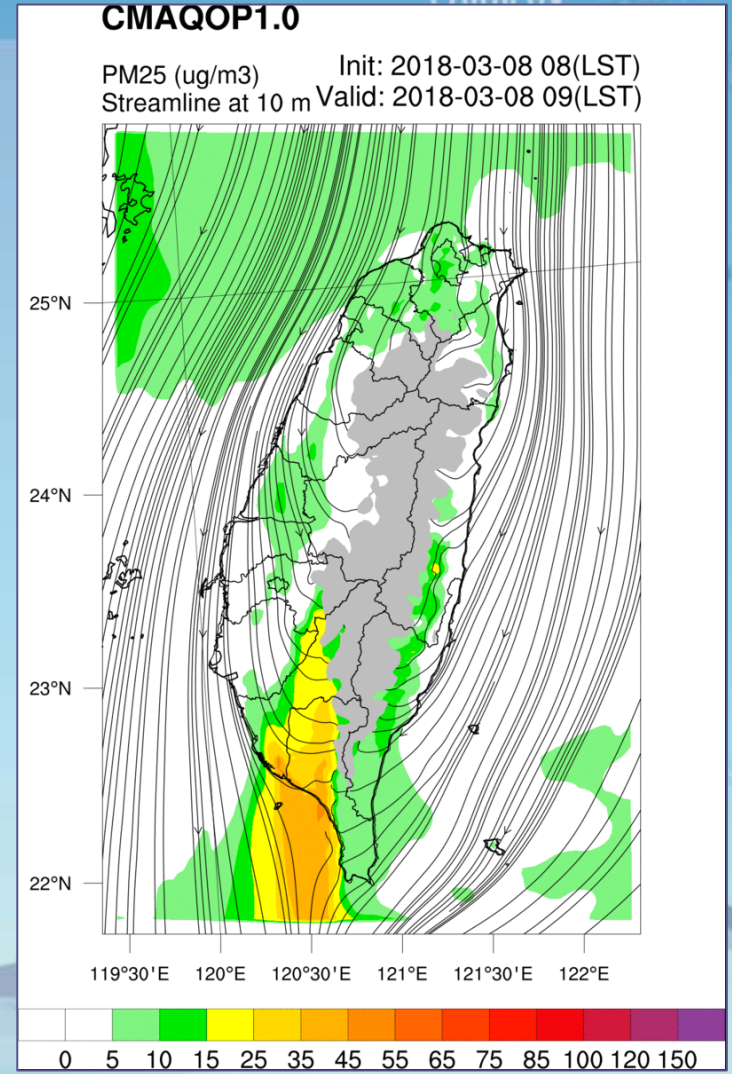
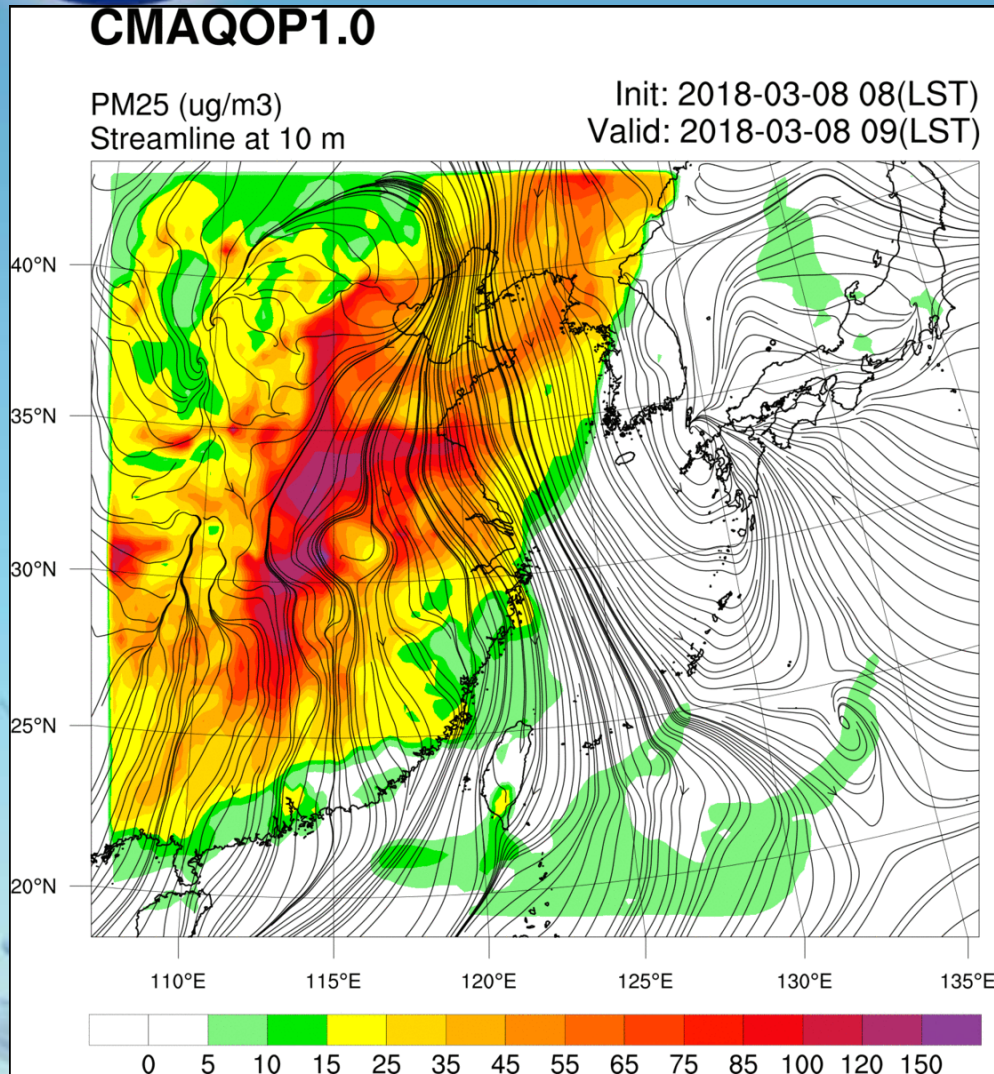
從過去的觀測
到未來的預報



Wea



空氣品質預報應用-PM_{2.5}



產品範例：多采公司提供



Applications

☀️ CWB NWP model output provides services in all aspects

- ✿ Hydrology, Flooding, and mudslide
- ✿ Air quality prediction
- ✿ Aviation services
- ✿ Ocean current and wave
- ✿ Search and Rescue Planning
- ✿ Disaster prevention and decision making

✿ ...

✿ **RENEWABLE ENERGY --- Let's work together**

展望

- ☀ 綠電的成功是營運，營運的效能是建立在預測的基礎
- ☀ 綠電的預測必須要有專責單位，以提供電力調度參考之用
 - ☁ 須有上位的政策支援
 - ☁ 以防災/空污預報可以為例對比
- ☀ 對預測的誤差要有詮釋和論述的能力
 - ☁ 量化預測的誤差（包括發電量與氣象預測）
 - ☁ 分析誤差的來源，擬定改善的策略
 - ☁ 預測多準才是準？
 - ☂ 預測不確定性的存在是必然，需配合預測準確度，擬定因應策略與風險管理作為